

Complex frequency,

Complex frequency

Definition: A type of frequency that depends on two parameters ; one is the " σ " which controls the magnitude of the signal and the other is " ω ", which controls the rotation of the signal ; is known as "complex frequency".

A complex exponential signal is a signal of type

$$X(t) = X_m e^{st} \longrightarrow \textcircled{1}$$

where X_m and s are time independent complex parameter. and

$$S = \sigma + j\omega$$

where X_m is the magnitude of $X(t)$

σ is the real part in S and is called neper frequency and is expressed in Np/s.

" ω " is the radian frequency and is expressed in rad/sec. " S " is called complex frequency and is expressed in complex neper/sec.

Now put the value of S in equation (1), we get

$$X(t) = X_m e^{\sigma t + j\omega t}$$

$$X(t) = X_m e^{\sigma t} e^{j\omega t}$$

By using Euler's theorem. we have i.e $e^{i\theta} = \cos \theta + i \sin \theta$

$$X(t) = X_m e^{\sigma t} [\cos(\omega t) + j \sin(\omega t)]$$

The real part is

$$X(t) = X_m e^{\sigma t} \cos(\omega t)$$

and imaginary part is

$$X(t) = X_m e^{\sigma t} \sin(\omega t)$$

The physical interpretation of complex frequency appearing in the exponential form will be studied easily by considering a number of special cases for the different value of S .

Case no 1:

When $w=0$ and σ has certain value, then, the real part is

$$X(t) = X_m e^{\sigma t} \cos(\omega t)$$

$$X(t) = X_m e^{\sigma t} \cdot 1 = X_m e^{\sigma t}$$

imaginary part is zero (0)

since

$$S = \sigma + j\omega$$

$$S = \sigma$$

as $\omega = 0$

Now there are also three cases in above case no 1

(i) If the neper frequency is positive i.e. $\sigma > 0$ the curve obtain is exponentially increasing curve as shown below.

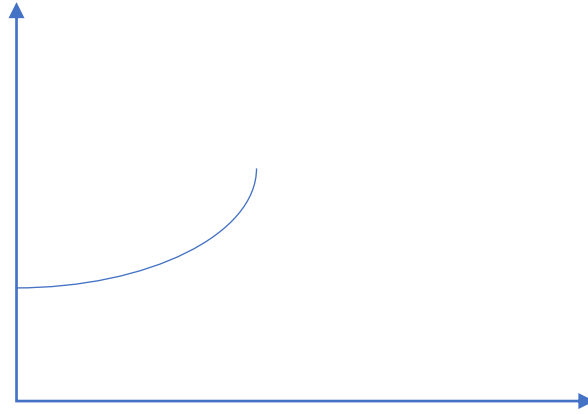


Fig:1

(ii) If $\sigma < 0$ then the curve obtain is exponentially decreasing curve as shown below

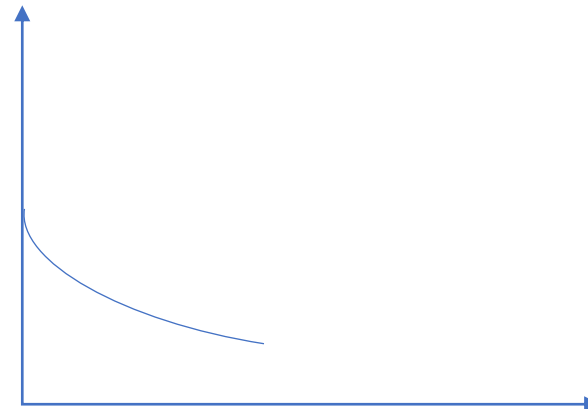


Fig:2

(iii) If $\sigma = 0$ then the curve obtain is the steady state d.c curve as shown below in fig:3

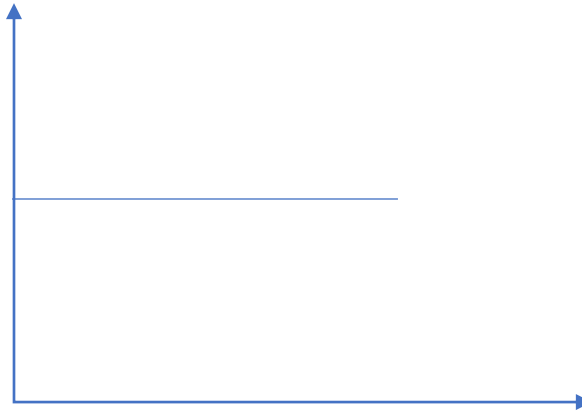
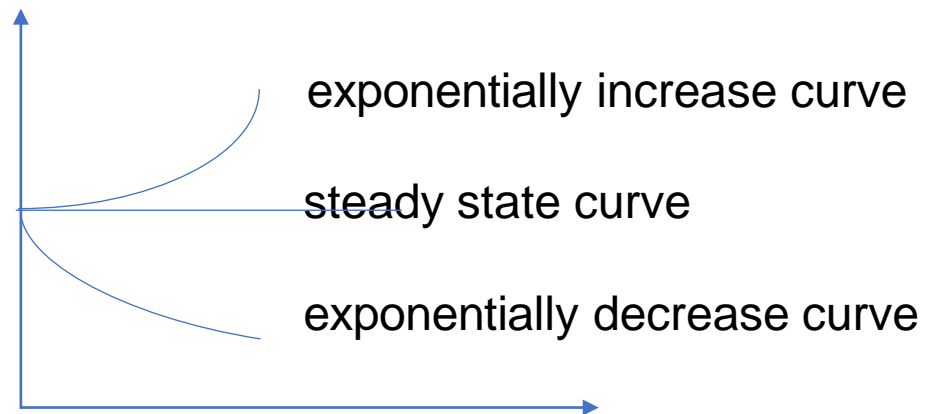


Fig:3

By combining all three curves we get



Case no 2

When $\sigma = 0$ and w has some value then, the real part is

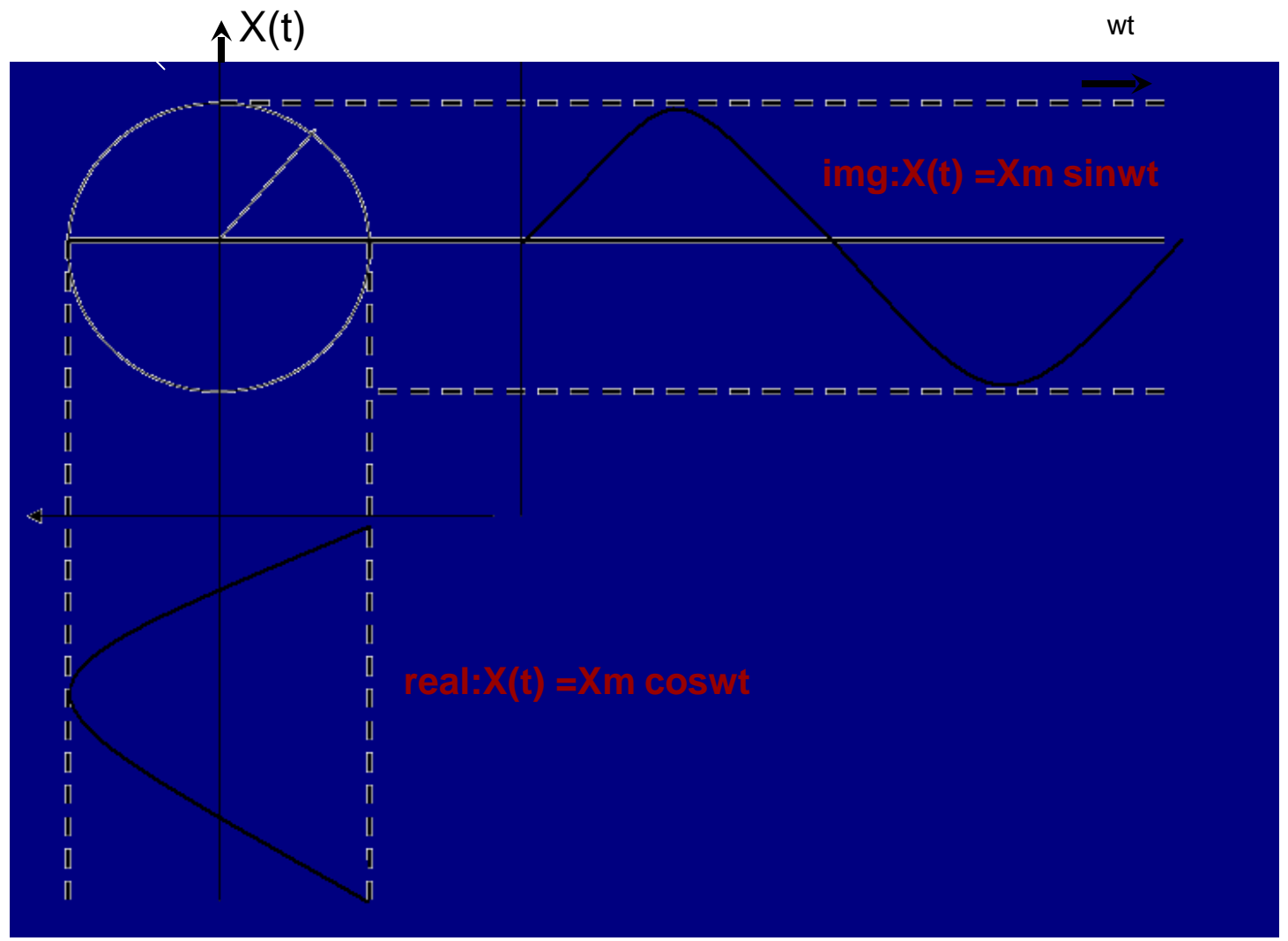
$$X(t) = X_m e^{0 \cdot t} \cos(\omega t)$$

$$X(t) = X_m \cos(\omega t)$$

and the imaginary part is

$$X(t) = X_m \sin(\omega t)$$

Hence the curve obtained is a sinusoidal steady state curve, as shown in the figure



Case no 3:

When σ and w both have some value, then the real part is

$$X(t) = X_m e^{\sigma t} \cos(\omega t)$$

and the imaginary part is

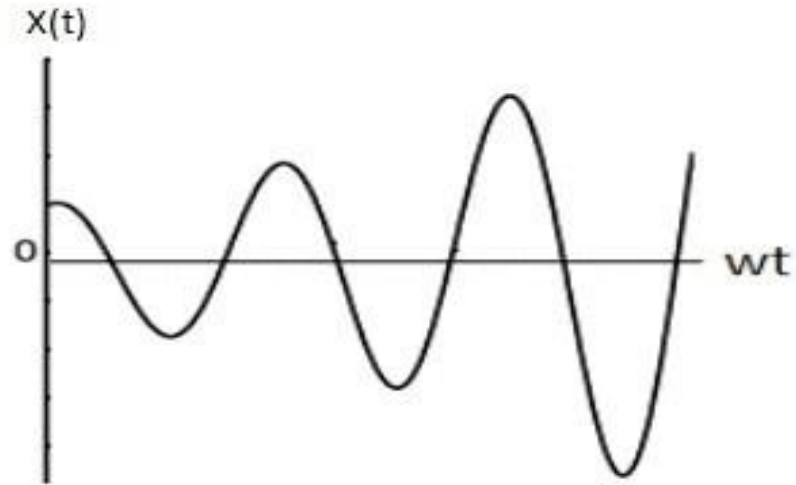
$$X(t) = X_m e^{\sigma t} \sin(\omega t)$$

So the curve obtained is time varying sinusoidal signal

These case no 3 is also has some two cases

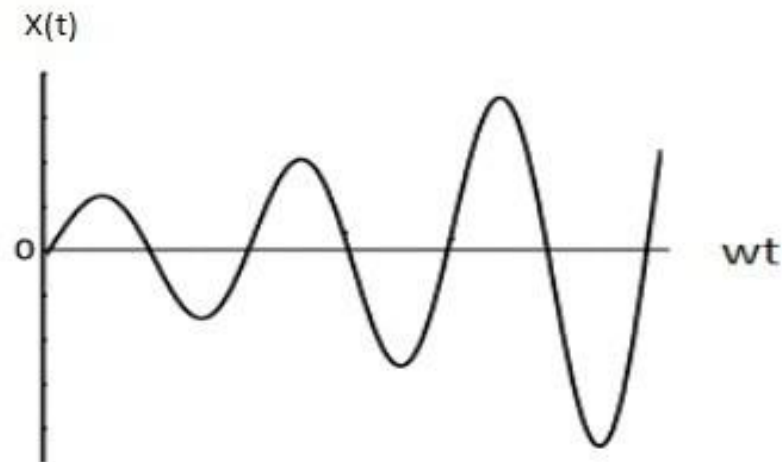
When $\sigma > 0$

REAL PART



$$X(t) = X_m e^{\sigma t} \cos(\omega t)$$

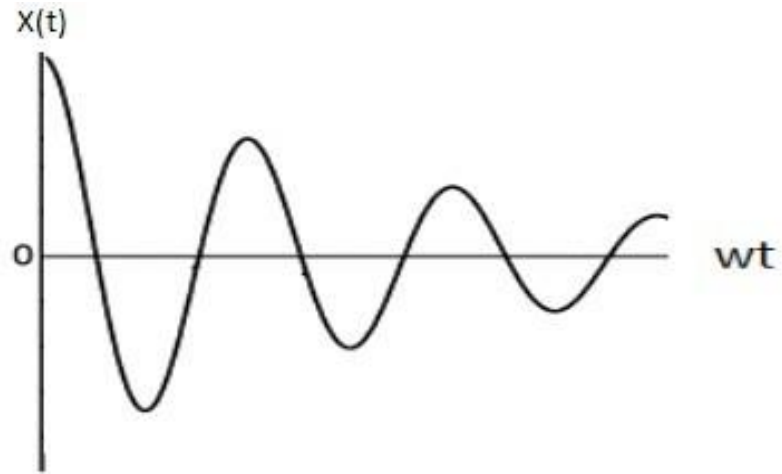
IMAGINARY PART



$$X(t) = X_m e^{\sigma t} \sin(\omega t)$$

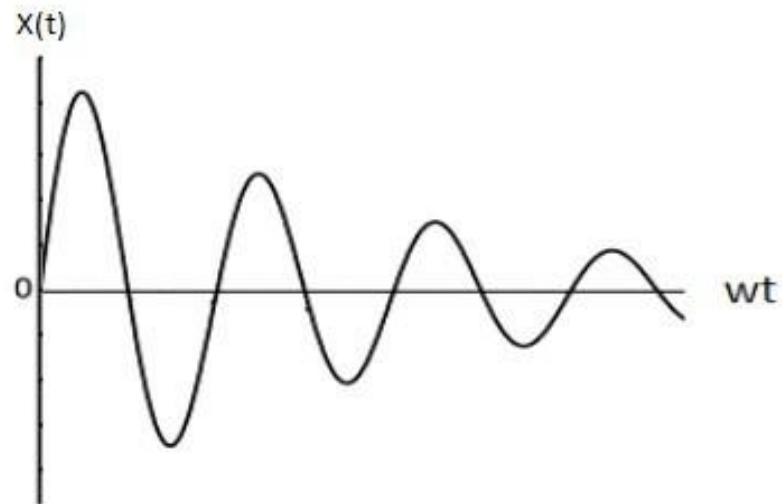
When $\sigma < 0$

REAL PART



$$X(t) = X_m e^{\sigma t} \cos(\omega t)$$

IMAGINARY PART



$$X(t) = X_m e^{\sigma t} \sin(\omega t)$$

Q : In the given circuit, Assume $R_1=1$ ohm, $R_2=2$ ohm and $C =1F$ Find

(i) Relation between $V_o(t)$ and $V_i(t)$

(ii) Find response to the following Input's

(a) $V_i(t) = 12\text{volt}$

(b) $V_i(t) = 12e^{-3t}$ volt

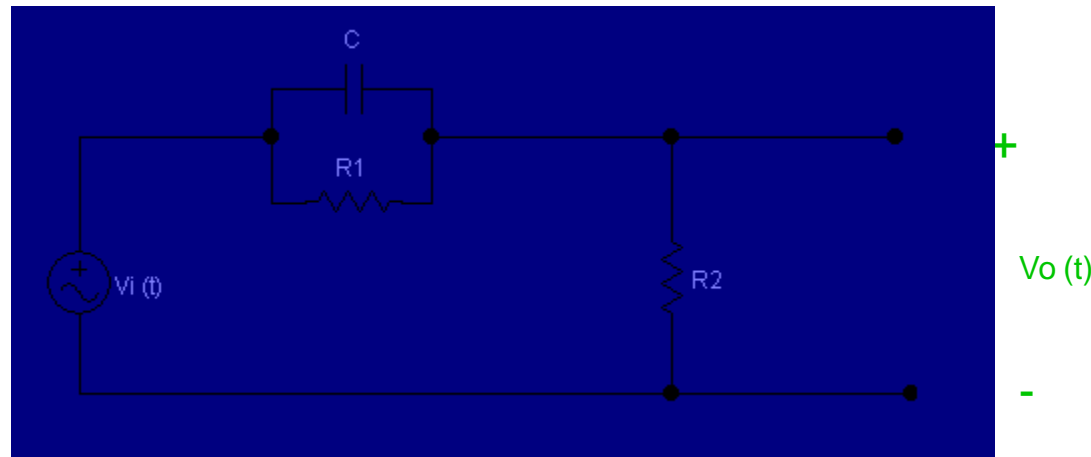
(c) $V_i(t) = 12e^{i2t}$ volt

(d) $V_i(t) = 12e^{(-3+j2)t}$ volt

(e) $V_i(t) = 10e^{-0.5t} \cos(1.5t)v$

Solution:

The given circuit is



(i) By applying Kcl on above ckt, we have

$$\frac{V_i - V_o}{R_1} + \frac{V_i - V_o}{1/c s} = \frac{V_o}{R_2}$$

By putting values of R_1, R_2 and C , we get

$$\frac{V_i - V_o}{1} + \frac{V_i - V_o}{1/s} = \frac{V_o}{2}$$

$$V_i - V_o + sV_i - sV_o = V_o/2$$

$$V_i(1+s) - s(1+V_o) = V_o/2$$

$$V_i(1+s) = V_o/2 + s(1+V_o)$$

$$V_i(1+s) = V_o(2s+3)/2$$

$$V_i(2+2s) = V_o\left(\frac{2s+3}{2}\right)$$

$$V_o(t) = \frac{(2s+2)}{(2s+3)} \times V_i(t)$$

(ii) Response to the following Input is given below:

(a) $V_i(t) = 12 \text{ volts}$

$$V_o(t) = \left[\frac{2(0) + 2}{2(0) + 3} \right] \times 12$$

as $\{e^0 = 1 \text{ \& } s = 0\}$

$$V_o(t) = 8 \text{ volt}$$

(b) $V_i(t) = 12e^{-3t}$

$$V_o(t) = \left[\frac{2(-3) + 2}{2(-3) + 3} \right] \times 12e^{-3t}$$

$$V_o(t) = 16e^{-3t} \text{ volt}$$

(c) $V_i(t) = 12e^{j2t} \text{ volt}$

$$V_o(t) = \left[\frac{2(2j) + 2}{2(2j) + 3} \right] 12e^{j2t}$$

$$V_o(t) = \left[\frac{4j+2}{4j+3} \times \frac{4j-3}{4j-3} \right] \times 12e^{j2t}$$

$$V_o(t) = 10.3 \angle 10.3^\circ \text{ volt}$$

(d) $V_i(t) = 12e^{(-3+j2)t}$ volt

$$V_o(t) = \left[\frac{2(-3+j2)+2}{2(-3+j2)+3} \right] \times 12e^{(-3+j2)t}$$

$$V_o(t) = 13.57 \angle 8.130^\circ e^{(-3+j2)t} \text{ volt}$$

(e) $V_i(t) = 10e^{-0.5t} \cos(1.5t+30)$

Since the given response voltage is of only real part & we know that

$$V_i(t) = X_m e^{\sigma t} \cos(\omega t)$$

and we have given

$$V_i = 10, \quad \sigma = -0.5, \quad \omega = 1.5,$$

Since $S = \sigma + j\omega$

$$S = -0.5 + j1.5$$

therefore

$$V_i(t) = 10 e^{(-0.5 + j1.5)t} \cos(1.5t)$$

$$V_o(t) = 10 e^{(-0.5 + j1.5)t} \left[\frac{2(-0.5 + j1.5) + 2}{2(-0.5 + j1.5) + 3} \right]$$

$$V_o(t) = 8.77 e^{(-0.5 + j1.5)t}$$

Finally

$$V_o(t) = 8.77 e^{-0.5t} (\cos 1.5t + j \sin 1.5t) \text{ volt}$$

