

Electric field:

Let a point charge 'q' is moved from point A to B in an Electric field E



from Coulomb's law,
force on charge, $F = qE$

∴ work done in displacing charge by dl ,

$$W = -\vec{F} \cdot d\vec{l} = -qE dl$$

-ve sign shows that work is done by external field.

Total work done in moving charge from 'A' to 'B'

$$W = -q \int_A^B E \cdot dl$$

$$\text{potential diff } V_{AB} = \frac{W}{q} = - \int_A^B E \cdot dl$$

→ If V_{AB} is -ve, there is loss in P.E.
i.e. work done by field.

→ If V_{AB} is +ve, there is gain in P.E.
i.e. work done by external agent.

→ V_{AB} is independent of path.

If field is produced by charge q located at origin,

$$E = \frac{q}{4\pi\epsilon_0 r^2} \hat{r}$$

$$V_{AB} = - \int_{r_A}^{r_B} \frac{q}{4\pi\epsilon_0 r^2} \hat{r} \cdot d\hat{r} r$$

$$= \frac{q}{4\pi\epsilon_0} \left[\frac{1}{r_B} - \frac{1}{r_A} \right]$$

$$V_{AB} = V_B - V_A$$

* vectors whose line integral does not depend on path of integration is called conservative.

Potential at distance r from origin is work done per unit charge by an external agent to bringing a test charge from infinity to that point.

$$V = - \int_{\infty}^r E \cdot dl \quad \text{(where } E \text{ given)}$$

If q_1, q_2, \dots, q_n are located at r_1, r_2, \dots, r_n potential at r , $V(r) = \frac{1}{4\pi\epsilon_0} \sum_{k=1}^n \frac{q_k}{|r - r_k|}$ (where q given)

Relation between E & V - Maxwell's eqn 2

$$V_{BA} = -V_B \Rightarrow V_{BA} + V_B = 0$$

$$\oint E \cdot dl = 0$$

→ line integral of E along closed path must be zero. Applying Stokes theorem.

$$\oint E \cdot dl = \int_S (\nabla \times E) \cdot d\vec{s} = 0$$

$\nabla \times E = 0 \rightarrow$ 2nd Maxwell eqn
 \Downarrow
 such field are

known as conservative or irrotational.
 Now, $dV = -E \cdot dl = -E_x dx - E_y dy - E_z dz$

$$dV = \frac{\partial V}{\partial x} dx + \frac{\partial V}{\partial y} dy + \frac{\partial V}{\partial z} dz$$

Comparing, $E_x = -\frac{\partial V}{\partial x}$, $E_y = -\frac{\partial V}{\partial y}$
 $E_z = -\frac{\partial V}{\partial z}$

$\therefore E = -\nabla V$
 where $E = (3x^2 + y)ax + xay \text{ kV/m}$
 $q = -2 \mu C$

$(0, 5, 0) \rightarrow (2, 5, 1, 0)$
 $(0, 5, 1, 0) \rightarrow (2, 5, 0)$

$\frac{W}{q} = - \int_C E \cdot dl \Rightarrow \frac{-W}{q} = \int_C E \cdot dl$

$A(0, 5, 0) \rightarrow B(2, 5, 0) \rightarrow C(2, 1, 0)$
 $dl = dx \text{ ax} \quad dl = dy \text{ ay}$

$W_{AC} = W_{AB} + W_{BC}$

$\therefore \frac{-W}{q} = \left(\int_{AB} + \int_{BC} \right) E \cdot dl$

$= \int_0^2 (3x^2 + y) dx \Big|_0^2 + \int_5^1 x dy$
 $y = 5, z = 0$
 $x = 2$

$= \frac{3x^3}{3} + 5x \Big|_0^2 + 2y \Big|_5^1$

$= 8 + 10 + (-2 - 10)$

$= 18 - 12 = 6$
 $W = -6q = 12 \mu J$

b) $y = 5 - 3x$

$dy = -3 dx$

$$E = (5x^2 + y)j + x^2y$$

$$\vec{r} = dx\hat{i} + dy\hat{j}$$

$$EM = (2x^2 + y)dx + x^2dy$$

$$= \int_2^5 (2x^2 + 5 - 2x)dx + \int_1^3 \frac{5-x}{3} dy$$

$$= \frac{2x^3}{3} + 5x - 2x^2 \Big|_2^5 + \int_2^5 \frac{5-x}{3} dy$$

$$= x^3 + 5x - \frac{2x^2}{2} \Big|_2^5 + \frac{5-x}{3} \Big|_1^3$$

$$= \left[\frac{5^3}{3} + 5 - \frac{2^3}{3} \right] - 2 + \frac{5-x}{3} \Big|_1^3$$

$$= 8 + 10 - \frac{2}{3} \times 4 - 0 + \frac{5-x}{3} \Big|_1^3$$

$$= \frac{8}{3} - \frac{2}{3} - \frac{2}{3} + \frac{25}{3} + \frac{25}{6}$$

$$= 18 - 6 - \frac{2}{3} + 4$$

$$= 12 + 10 + 4$$

$$= 6$$

$$W = 12 \text{ mJ}$$

material

conductor

5V D.C.

(large force ϵ)

Electrical insulators - conduct. electric charge

insulators

material that - stores electric charge, retaining

insulation, isotropic homogeneity, dielectric strength, relaxation time

conductivity - $\rho \rightarrow$ resist ρ

of $T = 0K$, some metal superconductors

$$\rho \propto T \cdot \rho$$

EX: Lead, Al

Lower surface conductivity:-

electric charge - ...

$$I = \frac{dq}{dt} \quad \text{V/S or } \mu^2$$

$$I = \frac{dQ}{dt} \Rightarrow \Delta I = I \cdot \Delta t$$

current density (J): of ΔI conductor

holes pass through ΔS surface.

$$J = \frac{\Delta I}{\Delta S} \Rightarrow \Delta I = I \cdot \Delta t$$

current density is I to surface

of net, $\Delta I = I \cdot \Delta t$

of net, $\Delta I = I \cdot \Delta t$

Total current,

$$I = \int_S \mathbf{J} \cdot d\mathbf{s}$$

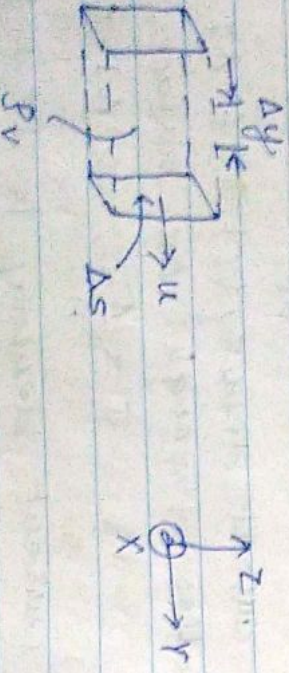
Circuit density \rightarrow correct current density
 \rightarrow conduct circuit
 \rightarrow displacement

\rightarrow Convection current does not involve conductor and does not satisfy Ohm's law.

\rightarrow It occurs when flow through insulating medium such as liquid, saturated gas, or vacuum.

Consider a filament of charge density ρ_v velocity of flow of charge $u = u_y \hat{y}$

$$\Delta I = \frac{\Delta Q}{\Delta t} = \rho_v \cdot \Delta S \frac{\Delta y}{\Delta t} = \rho_v \Delta S \cdot u_y$$



$$\mathbf{J}_y = \frac{\Delta I}{\Delta S} = \rho_v u_y$$

$$\mathbf{J} = \rho_v \mathbf{u}$$

\mathbf{J} is convection current and ρ_v is convection current density.

Conduction current:

It requires a conductor. When 'E' field is applied, the force on electron of charge $-e$ is:

$$\mathbf{F} = -e\mathbf{E}$$

Electron will experience collision with atoms lattice. Let m is the mass moving in E-field with velocity u .

Rate of change of momentum

$$\rightarrow u = \frac{-e\mathbf{E}t}{m}$$

where τ is the average time interval between collision. u is the drift velocity of e^- . Let charge conc. is n .

$$\text{then } \rho_v = -ne$$

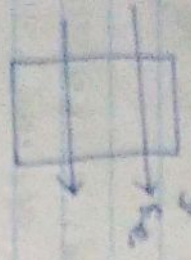
conduction current density,

$$\mathbf{J} = \rho_v \cdot \mathbf{u} = \frac{ne^2 \tau}{m} \mathbf{E} = \sigma \mathbf{E}$$

$\mathbf{J} = \sigma \mathbf{E}$ Ohm's law in vector form

Conductors

external electric field



Isolated conductor.

Due to E_e , the charges are displaced along E_e and -ve free charge in opposite dir.

- (1) Free charge accumulate on the surface of conductor ~~and~~ forming surface induced charge.
- (2) Induced charges produce internal E-field, which cancel E_e .

$$E = -\nabla V = 0$$

Conductor is called equipotential body.

Another way:

$$J = \sigma E$$

for perfect conductor, $\sigma = \infty$

$$\therefore E = 0$$

→ If some charge is introduced inside conductor (+) redistribute on surface such that E field inside is zero.

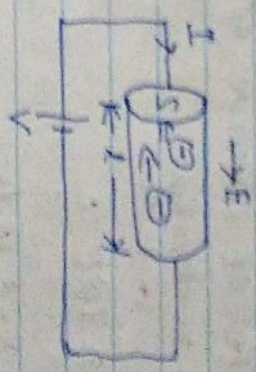
From Gauss Law;

$$E_0 \text{ then } J_0 = 0.$$

Hence under static condition:-

$$E = 0, \quad J = 0, \quad V_{int} = 0$$

↳ Inside Conductor



Taking a conductor whose ends are maintained potential difference V .

Here, $E \neq 0$ inside conductor, since there is no static equilibrium. i.e. conductor is not isolated and wired to a source of electromotive force, which prevents establishment of electrostatic equilibrium. → Dir of E is same dir of flow of the charge.

$$E = \frac{V}{l}$$

$$J = \frac{I}{S}$$

$$\rightarrow \sigma E = \frac{I}{S}$$

$$\sigma \frac{V}{l} = \frac{I}{S} \rightarrow \frac{V}{I} = \frac{l}{\sigma S} = \frac{\rho l}{S}$$

$R_0 \rightarrow$ Resistivity.

$$R = \frac{\rho_0 l}{S} \rightarrow \text{Applicable when uniform cross section.}$$

For any, $R = \frac{V}{I} = \frac{\int E \cdot dl}{\int J \cdot ds}$

Power (P) \rightarrow Rate of change of energy
or, Force \times velocity.

$$P = \int \mathbf{J} \cdot d\mathbf{V} \cdot \mathbf{E} \cdot \mathbf{u}$$

$$= \int \mathbf{E} \cdot \mathbf{J} \cdot d\mathbf{V}$$

$$P = \int \mathbf{E} \cdot \mathbf{J} \cdot d\mathbf{V}$$

Joule's Law:

Power density $w_p = \frac{dP}{dV} = \mathbf{E} \cdot \mathbf{J}$
 $= \sigma E^2$ (*)

$$dV = ds \cdot dl$$

$$P = \int \mathbf{E} \cdot d\mathbf{l} \int \mathbf{J} \cdot ds$$

$$= VI$$

$$P = I^2 R \rightarrow \text{Joule's Law.}$$

Ques: If $J = \frac{1}{r^2} [2 \cos \theta \mathbf{a}_r + \sin \theta \mathbf{a}_\theta]$ find

calculate current passing through:

(a) Hemispherical shell of radius R ,
 $0 < \theta < \pi/2$; $0 < \phi < 2\pi$

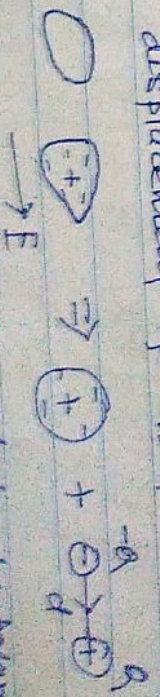
(b) spherical shell of radius 10 cm.

Soln: $I = \int \mathbf{J} \cdot ds$
 $ds = r^2 \sin \theta d\theta d\phi$

Ques: For the current density $J = 10z \mathbf{a}_{\phi}$ in the cylindrical surface $\rho = 2$, $1 \leq z \leq 5$ m.

Polarization in Dielectrics:

In dielectric materials nuclei in molecules taken as fixed charge and electrons structure as single cloud of negative charges surrounding to the atom. When E field is applied force exerted by dielectric is $F = qE$, and a dipole results from the displacement of charges.



Dielectrics is said to be polarized

Dipole moment, $P = qd$

If there are N dipoles in volume ΔV of dielectric.

Total dipole moment = $\sum_{k=1}^N q_k d_k$

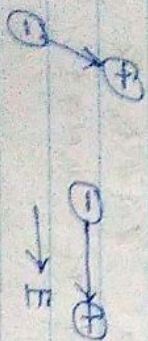
Polarization 'P' is dipole moment per unit volume.

$$P = \frac{\sum_{k=1}^N q_k d_k}{\Delta V}$$

This type of dipole is called non polar where otherwise there is no dipole before applying E-field. In presence of E all dipoles aligned in the direction of E-field.

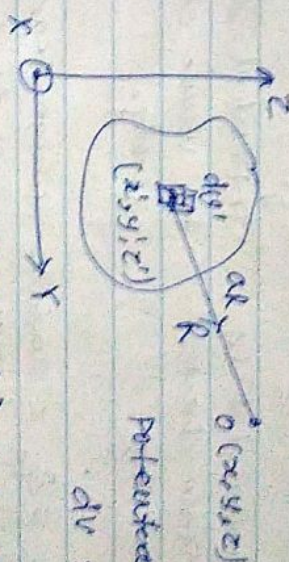
Ex: H_2O, N_2, CO_2 gas.

→ Polarized dielectrics are those having built-in dipoles and aligned in the direction of E-field when E is applied.



Electric field due to polarized dielectric

$P =$ Dipole moment per unit volume.



Potential due to dV'

$$dV = \frac{P \cdot dV'}{4\pi\epsilon_0 R^2}$$

where $R^2 = (x-x')^2 + (y-y')^2 + (z-z')^2$

Since $\nabla \left(\frac{1}{R} \right) = \frac{-\mathbf{R}}{R^3}$ gradient

$$\therefore dV = \frac{1}{4\pi\epsilon_0} P \cdot \nabla \left(\frac{1}{R} \right) dV'$$

Since, $\nabla \cdot \mathbf{A} = \int \nabla \cdot \mathbf{A} + \mathbf{A} \cdot \nabla$

$$\rightarrow \mathbf{A} \cdot \Delta f = \nabla \cdot \mathbf{A} f - \int \nabla \cdot \mathbf{A}$$

$$\therefore dV = \frac{1}{4\pi\epsilon_0} \left[\nabla \cdot \left(\frac{1}{R} P \right) - \frac{1}{R} \nabla \cdot P \right]$$

Total potential :-

$$V = \frac{1}{4\pi\epsilon_0} \int \left[\nabla \cdot \left(\frac{P}{R} \right) - \frac{\nabla \cdot P}{R} \right] dV'$$

$$\int \nabla \cdot \left(\frac{P}{R} \right) dV' = \int \frac{P \cdot \mathbf{a}_n}{R} dS \quad (\text{Divergence theorem})$$

ρ_{ext} is the unit normal to surface dS'

$$\therefore V = \int_{S'} \frac{\rho_{\text{ext}} \cdot dS'}{4\pi\epsilon_0 R} + \int_{V'} \frac{-\nabla \cdot P}{4\pi\epsilon_0 R} dV'$$

↓ Potential due to surface charge density
↓ Potential due to volume charge density

$P_{\text{ext}} = P_{\text{ext}}$ = surface charge density over surface of dielectric

$\nabla \cdot P = P_{\text{ext}}$ Volume throughout the dielectric.

Thus one bound charges, total bound charge on surface,

$$Q_{\text{ext}} = \oint P \cdot dS = \int_{S'} \rho_{\text{ext}} dS$$

outside volume

$$-Q_{\text{b}} = \int_V \rho_{\text{ext}} dV = -\int_V \nabla \cdot P dV$$

If P_{ext} is the free charge density

for the dielectric.

total volume charge density,

$$\rho_{\text{ext}} = \rho_{\text{ext}} + \rho_{\text{ext}} = 2\rho_{\text{ext}}$$

$$= 2\rho_{\text{ext}}$$

$$\therefore E_{\text{ext}} = \frac{1}{4\pi\epsilon_0} \frac{2\rho_{\text{ext}}}{r^2}$$

$$= \frac{1}{2\pi\epsilon_0} \frac{\rho_{\text{ext}}}{r^2}$$

$$\therefore D = \epsilon_0 E + P$$

P can also be written as -

$$P = \chi_e \epsilon_0 E$$

$\chi_e =$ Electric susceptibility of material.

material.

$$D = \epsilon_0 E + \chi_e \epsilon_0 E$$

$$= \epsilon_0 [1 + \chi_e] E$$

$$= \epsilon_0 \epsilon_r E$$

$$D = \epsilon_r E$$

$$\epsilon_r = 1 + \chi_e = \frac{\epsilon_r}{\epsilon_0}$$

The dielectric constant (or relative permittivity) is the ratio of the permittivity of dielectric to that of free space.

→ The dielectric strength is the maximum electric field that a dielectric can tolerate, ~~or~~ without electrical breakdown.

break down.

Continuity eqn:-

charge conservation - rate of decrease

of charge within a given volume must be equal to net outward

current flow through the surface of volume.

∴ current coming out of surface,

$$I_{out} = \oint \sigma \cdot dS = -\frac{dQ_{in}}{dt}$$

from divergence theorem,

$$\oint \sigma \cdot dS = \int \nabla \cdot \mathbf{J} \cdot dV$$

$$-\frac{dQ_{in}}{dt} = -\frac{d}{dt} \int \rho \cdot dV = -\int \frac{d\rho}{dt} \cdot dV$$

$$\therefore \int \nabla \cdot \mathbf{J} \cdot dV = -\int \frac{d\rho}{dt} \cdot dV$$

$$\boxed{\nabla \cdot \mathbf{J} = -\frac{d\rho}{dt}} \rightarrow \text{continuity eq.}$$

For steady current, $\frac{d\rho}{dt} = 0$

$$\nabla \cdot \mathbf{J} = 0$$

total charge leaving = total charge entering.

(KCL)

Max. Ohm's law $\Rightarrow \mathbf{J} = \sigma \mathbf{E}$

$$\text{Gauss's law} \Rightarrow \nabla \cdot \mathbf{E} = \frac{\rho}{\epsilon}$$

from continuity eq.:

$$\nabla \cdot \sigma \mathbf{E} = \frac{\sigma \rho}{\epsilon} = -\frac{\partial \rho}{\partial t}$$

$$\rightarrow \frac{d\rho}{dt} + \frac{\sigma \rho}{\epsilon} = 0.$$

$$\rightarrow \frac{d\rho}{\rho} = -\frac{\sigma}{\epsilon} dt$$

integrating, $\ln \rho = -\frac{\sigma t}{\epsilon} + \ln \rho_0$

↑
const.

$$\rho = \rho_0 e^{-t/\tau}$$

$$\text{where, } \tau = \frac{\epsilon}{\sigma}$$

ρ_0 is initial charge at $t=0$.
Time const. τ is relaxation time.

Relaxation time: it is the time taken so that a charge placed in interior of material drops to e^{-1} (36.8%) of its initial value.

Boundary Conditions:-

Interface:-

Dielectric (ϵ_1) & Dielectric (ϵ_2)

conductor & free space.

cancel out leaving out of surface,

$$\text{Total} = \oint \sigma \cdot dS = -\frac{dQ_{\text{enc}}}{dt}$$

from divergence theorem,

$$\oint \sigma \cdot dS = \int \nabla \cdot \mathbf{J} dV$$

$$-\frac{dQ_{\text{enc}}}{dt} = -\frac{d}{dt} \int \rho dV = -\int \frac{d\rho}{dt} \cdot dV$$

$$\therefore \int \nabla \cdot \mathbf{J} dV = -\int \frac{d\rho}{dt} dV$$

$$\boxed{\nabla \cdot \mathbf{J} = -\frac{d\rho}{dt}} \rightarrow \text{continuity eq.}$$

For steady current, $\frac{d\rho}{dt} = 0$

$$\nabla \cdot \mathbf{J} = 0$$

total charge leaving = total

charge entering.

(KCL)

Also,

$$\text{Ohm's Law} \Rightarrow \mathbf{J} = \sigma \mathbf{E}$$

$$\text{Gauss' Law} \Rightarrow \nabla \cdot \mathbf{E} = \frac{\rho}{\epsilon}$$

from continuity eq.:

$$\nabla \cdot \mathbf{J} = \nabla \cdot (\sigma \mathbf{E}) = -\frac{\partial \rho}{\partial t}$$

$$\nabla \cdot (\sigma \mathbf{E}) = \frac{\partial \rho}{\partial t}$$

$$\nabla \cdot (\sigma \mathbf{E}) = -\frac{\partial \rho}{\partial t}$$

Integrating, $\int \nabla \cdot (\sigma \mathbf{E}) dV = -\frac{dQ_{\text{enc}}}{dt}$

$$\int \nabla \cdot (\sigma \mathbf{E}) dV = -\frac{dQ_{\text{enc}}}{dt}$$

$$\text{Gauss' Law} \Rightarrow \int \nabla \cdot \mathbf{E} dV = \frac{Q_{\text{enc}}}{\epsilon}$$

ρ_{enc} is total charge at $t=0$
Thus const. ρ is retained the

character from. It is the same then

so that a charge placed in volume
of material to keep it $\epsilon^{-1} \rho_{\text{enc}}$
if it's initial value.

Boundary Condition:-

Interface:

Dielectric (ϵ_1) & Dielectric (ϵ_2)

Conductor & Conductor

0.5

6

0.5

free space

Pressure's are:

$$\int F_1 dA = 0$$

$$\int P_2 dA = R_{interfacial}$$

$$P = P_1 + P_2 \rightarrow \text{normal comp}$$

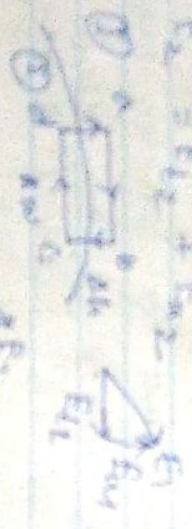
Therefore - Interface boundary conditions -

At two different medium are characterized by interface comp. $\epsilon_1 = \epsilon_0 \epsilon_r$

E_1 and E_2 are the E-fields in media 1 & 2, respectively.

$$E_1 = E_{e1} + E_{a1}$$

$$E_2 = E_{e2} + E_{a2}$$



$$\oint C \cdot dA = 0$$



$$\rightarrow P_1 \Delta A_1 - P_2 \Delta A_2 + \frac{F_{a1} \Delta A_1}{\Delta A} \uparrow$$

$$- E_{a1} \Delta A_1 - E_{a2} \Delta A_2 + E_{a1} \Delta A_1$$

$$E_{a1} \Delta A_1 - E_{a2} \Delta A_2 = 0$$

$$\rightarrow P_1 = P_2$$

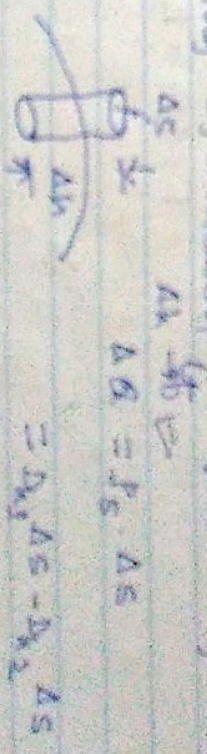
→ Tangential components of E-fields are continuous across the boundary.

$$D = \epsilon E = D_1 + D_2$$

$$\therefore \frac{D_1}{\epsilon_1} = \frac{D_2}{\epsilon_2}$$

D undergoes some change across the interface. Hence D is discontinuous across the boundary.

Taking of bounded Gaussian surface:



$$\rightarrow [D_1 A - D_2 A] = q_{enc}$$

P_2 is the free charge density at the surface of bounding.

If no free charge exist, then

$$D_{n1} = D_{n2}$$

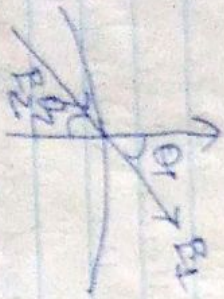
→ No normal component of D is continuous across the surface.

$$D = \epsilon E$$

$$\therefore \epsilon_1 E_{n1} = \epsilon_2 E_{n2}$$

Normal components of E is discontinuous at boundary.

Reflection of E-field at boundary:



$$E_{t1} = E_{t2}$$

$$E_1 \sin \theta_1 = E_2 \sin \theta_2$$

$$D_{n1} = D_{n2}$$

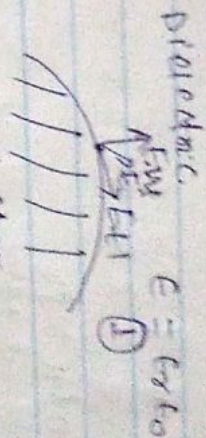
$$\epsilon_1 E_1 \cos \theta_1 = \epsilon_2 E_2 \cos \theta_2$$

Dividing

$$\frac{\epsilon_1 E_1 \cos \theta_1}{\epsilon_2 E_2 \cos \theta_2} = \frac{\epsilon_1 E_1 \sin \theta_1}{\epsilon_2 E_2 \sin \theta_2}$$

Ques: Two adjoining homogeneous

conductor-dielectric boundary condition



Dielectric

$$\epsilon = \epsilon_0 \epsilon_r$$

$$E_{t1} = E_{t2}$$

conductor

$$E = 0$$

$$\rightarrow E_{t1} = 0$$

$$D_n = D_n \Delta S = \rho_f \Delta S$$

$$D_n = \frac{\rho_f \Delta S}{\Delta S} = \rho_f$$

$$D_n = \rho_f$$

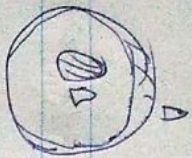
→ No electric field exist inside conductor

→ No P.D. within conductor
 $E = -\nabla V = 0$

→ An electric field E must be external to the conductor and must be normal to its surface.

i.e. $D_t = \epsilon_0 \epsilon_r E_t = 0$

$$D_n = \epsilon_0 \epsilon_r E_n = \rho_f$$



Conductor - free space, boundary conductor

$$D_f = \epsilon_0 E_f = 0$$

$$D_w = \epsilon_0 E_w = P_s$$

Ans: $z < 0$

$$z > 0 ; \epsilon_{r1} = 4$$

$$z < 0 ; \epsilon_{r2} = 3$$

$$E_1 = 5q_x - 2q_y + 3q_z \text{ KVM ; } z > 0$$

Normal comp. $\rightarrow q_z$

$$E_{w1} = E_1 \cdot a_n = E_1 \cdot q_z = 3$$

$$E_{w2} = 3q_z$$

$$E_{w2} = (E_2 \cdot q_z) q_z$$

$$E = E_{w1} + E_{w2}$$

$$E_{t1} = E_1 - E_{w1} = 5q_x - 2q_y$$

$$E_{t2} = E_{t1} = 5q_x - 2q_y$$

$$P_{w2} = D_{w2}$$

$$\epsilon_{r2} E_{w2} = \epsilon_{r1} E_{w1}$$

$$\rightarrow E_{w2} = \frac{\epsilon_{r1} \epsilon_{r2}}{\epsilon_{r2}} = 4q_z$$

$$\therefore E_2 = 5q_x - 2q_y + 4q_z \text{ KVM}$$

$$E_{w1} = 3$$

$$E_{t1} = \sqrt{25 + 4} = \sqrt{29}$$

$$\tan \theta_1 = \frac{E_{w1}}{E_{t1}} = \frac{3}{\sqrt{29}}$$

$$\tan \theta_2 = \frac{E_{t2}}{E_{w2}}$$

Laplace and Poisson's eqⁿ

\rightarrow Most common charge distribution is a volume charge

\rightarrow Laplace and Poisson's eqⁿ are used to solve differential eqⁿ relating the voltage developed due to a volume charge.

Let ΔV - for volume.

$$E = -\nabla V$$

$$D = \epsilon E$$

$$\nabla \cdot D = \rho$$

Def $\nabla \cdot (EE) = \rho_v$
 $\nabla \cdot (\epsilon \nabla V) = \rho_v$

when ϵ is const.

$$\nabla \cdot \nabla V = -\frac{\rho_v}{\epsilon}$$

$$\boxed{\nabla^2 V = -\frac{\rho_v}{\epsilon}} \Rightarrow \text{Poisson's eqn.}$$

when $\rho_v = 0$ i.e. charge free region.

$$\nabla^2 V = 0$$

→ This is called Laplace eqn.

→ Laplace and Poisson's eqs are 2nd order differential eqs and they always have a single soln. Indiv. dually because voltage is always defined at a point. This is called uniqueness theorem.

$$\nabla^2 V = \frac{1}{h_1 h_2 h_3} \left[\frac{\partial}{\partial u} \left(\frac{h_2 h_3}{h_1} \frac{\partial V}{\partial u} \right) + \dots \right]$$

$$\frac{\partial}{\partial v} \left(\frac{h_3 h_1}{h_2} \frac{\partial V}{\partial v} \right) + \frac{\partial}{\partial w} \left(\frac{h_1 h_2}{h_3} \frac{\partial V}{\partial w} \right)$$

x	y	z	1	1	1
p	φ	z	1	φ	1
r	θ	φ	1	r	sinθ
u	v	w	1	h ₁	h ₂

capacitors:-

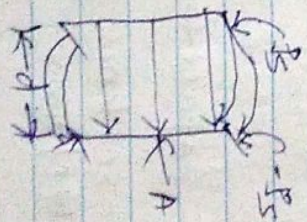
capacitance is the ability to hold E field containing it to a small region.

- special geometry:-
- parallel plate
- concentric cylinders
- concentric spheres

$$C = \frac{Q}{V} = \frac{\int \rho \cdot d\tau}{\int E \cdot dl} = \frac{\epsilon \int \rho \cdot d\tau}{\int E \cdot dl}$$

→ capacitance is the ratio of charge utilized and the potential developed due to the charge.

Parallel plate capacitor:-



$A \gg d$

→ E is uniform across the edge of plate known as fringing effect.

$$\rho_s = \frac{Q}{S}$$

If we ignore fringing at the edge of the plate then $|\mathbf{D}| = \rho_s$

$$E = \frac{1}{\epsilon} = \frac{V}{Ad}$$

$$V = \frac{Qd}{\epsilon A}$$

$$\therefore C = \frac{Q}{V} = \frac{\epsilon A}{d}$$

Energy stored,

$W_E =$ total energy of E-field

$$= \left(\frac{1}{2} \epsilon E^2 \right) (Ad)$$

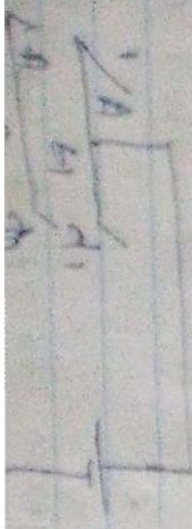
$$= \frac{1}{2} \frac{\epsilon A}{d} (Ed)^2$$

$$= \frac{1}{2} CV^2$$

$$= \frac{Q^2}{2C}$$

$$= \frac{1}{2} QV$$

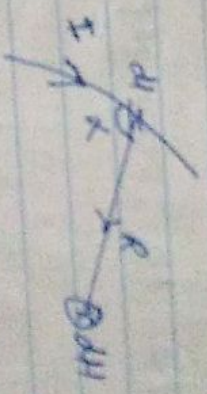
Multiplic dielectrics in capacitor parts
 Total area of cross-section and
 several width of dielectrics



Net capacitor over the sources
 due to voltage division

$$C_{eq} = \frac{Q_0}{V_0} = \frac{\epsilon_1 A \cdot \frac{V_0}{d_1}}{\frac{V_0}{d_1} + \frac{\epsilon_2 A}{d_2}}$$

Biot - savart's Law:-

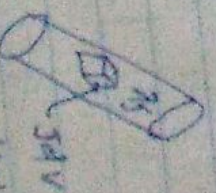
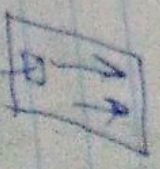
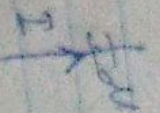


$$dH \propto \frac{Idl \sin \theta}{r^2}$$

$$dH = \frac{\mu_0 I dl \sin \theta}{4\pi r^2}$$

$$dH = \frac{1}{4\pi} \frac{Idl \times r}{r^3}$$

Case out distribution:-



R^2 surface

Voltage current

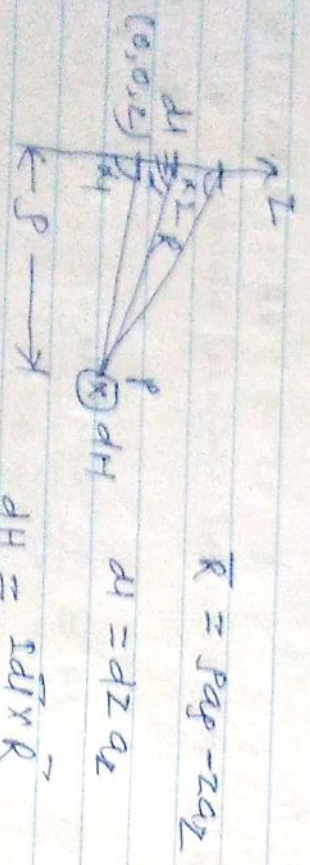
$K \rightarrow$ surface current density A/m
 $J \rightarrow$ volume A/m^2

$H = \frac{\int Idl \times a_R}{4\pi R^2}$ line current

$H = \frac{\int K ds \times a_R}{4\pi R^2}$ surface "

$H = \frac{\int J dV \times a_R}{4\pi R^2}$ Volume current.

Magnetic field due to straight line current :-



$dH = \frac{Idl \times R}{4\pi R^3}$
 $dH = \frac{Idz' a_z \times R}{4\pi R^3}$

Total magnetic field

$H = \int \frac{Idz'}{4\pi [z^2 + z'^2]^{3/2}} a_\phi$

$H_{max} = \frac{I}{z}$
 $\rightarrow z = \rho \cot \alpha$

$d_2 = -\rho \cot \alpha_2 \cdot dx$

$H = -\frac{I}{4\pi} \int_{\alpha_1}^{\alpha_2} \frac{\rho \cos \alpha \sin \alpha \cdot dx}{\rho^3 \cos^3 \alpha} a_\phi$
 $= -\frac{I}{4\pi \rho} \int_{\alpha_1}^{\alpha_2} \sin \alpha \cdot dx$

$H = \frac{I}{4\pi \rho} (\cos \alpha_2 - \cos \alpha_1) a_\phi$

\rightarrow when the conductor is semi-infinite
 i.e. $(0, 0, 0)$ to $(0, 0, \infty)$ $\alpha_1 = 90^\circ$ $\alpha_2 = 0$

$H = \frac{I}{4\pi \rho} a_\phi$

When conductor is of infinite length
 $(0, 0, -\infty)$ to $(0, 0, \infty)$

$\alpha_1 = 180^\circ$ $\alpha_2 = 0^\circ$

$H = \frac{I}{2\pi \rho} a_\phi$

H field is along concentric circular path.

Ampere's circuit law: Maxwell eqn:

\rightarrow Line integral of magnetic field H around a close path is same as the net current I enclosed by path.

$$\oint \mathbf{H} \cdot d\mathbf{l} = I$$

Applying Stokes theorem -

$$\oint \mathbf{H} \cdot d\mathbf{l} = \int (\nabla \times \mathbf{H}) \cdot d\mathbf{s}$$

$$I = \int \mathbf{J} \cdot d\mathbf{s}$$

$$\therefore \int \mathbf{J} \cdot d\mathbf{s} = \int (\nabla \times \mathbf{H}) \cdot d\mathbf{s}$$

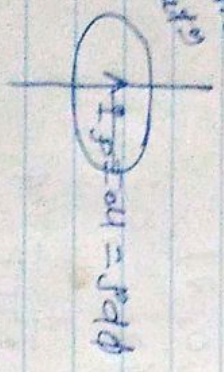
$$\rightarrow \int \nabla \times \mathbf{H} = \mathbf{J} \quad \text{Maxwell's 2nd}$$

3rd Maxwell's eqⁿ.

Application: - Infinite line current -

$$I = \oint \mathbf{H} \cdot d\mathbf{l}$$

Symmetric
distribution



$$\begin{aligned} \int \mathbf{H} \cdot d\mathbf{l} &= \int H dl \\ &= H \int dl \\ &= H \int 2\pi r \\ &= H \cdot 2\pi r \end{aligned}$$

$$H = \frac{I}{2\pi r}$$

Magnetic flux density:-

$$\mathbf{B} = \mu_0 \mathbf{H}$$

μ_0 is the permeability of free space.

Current \rightarrow A/m.

$$\mu_0 = 4\pi \times 10^{-7} \text{ H/m}$$

Magnetic flux through a surface,

$$\phi = \int \mathbf{B} \cdot d\mathbf{s}$$

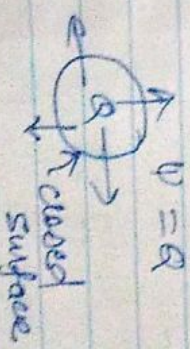
Wb

$$\mathbf{B} \rightarrow \text{Wb/m}^2$$

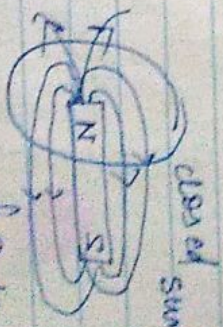
\rightarrow Magnetic flux line is path to which \mathbf{B} is tangential at every point on line.



Magnetic flux line



closed surface



closed surface

\rightarrow All isolated magnetic charges do not exist.

$$\oint \mathbf{B} \cdot d\mathbf{s} = 0$$

$$\Rightarrow \int \nabla \cdot \mathbf{B} \cdot d\mathbf{v} = 0 \Rightarrow \nabla \cdot \mathbf{B} = 0 \quad \text{Maxwell's fourth}$$

Maxwell eqs for static fields:

Differentiated form Integral Form.

$\nabla \cdot D = \rho$ $\oint D \cdot d\mathbf{s} = q$ Gauss Law

~~$\nabla \cdot B = 0$~~ $\oint E \cdot d\mathbf{l} = 0$ Closed surface nature of E-field

$\nabla \times E = 0$

$\nabla \times H = J$ $\oint H \cdot d\mathbf{l} = I$ Ampere's Law

~~$\nabla \times B = \mu_0 J$~~ $\oint B \cdot d\mathbf{s} = 0$ \uparrow Non-existence of monopoles

Magnetic scalar and vector potentials

Magnetic potential may be vector or scalar V_m .

since, $\nabla \times (\nabla V) = 0$

$\nabla \cdot (\nabla \times A) = 0$

for scalar V and vector A .

similar to $E = -\nabla V$

$H = -\nabla V_m$ if $J = 0$.

$J = \nabla \times H = \nabla \times (-\nabla V_m) = 0$

$\nabla^2 V_m = 0$

vector magnetic potential,

$\nabla \cdot B = 0$

$B = \nabla \times A$

so that $\nabla \cdot (\nabla \times A) = 0$.

Now, similar to, $V = \int \frac{dq}{4\pi\epsilon_0 r}$

$A = \int \frac{\mu_0 I d\mathbf{l}}{4\pi R}$ for line current

$= \int \frac{\mu_0 k d\mathbf{l}}{4\pi R}$ surface volume

Magnetic flux, $\psi = \int \mathbf{e} \cdot d\mathbf{a}$

$$= \int (\nabla \times \mathbf{A}) \cdot d\mathbf{a}$$

Applying Stokes's theorem.

$$\psi = \oint \mathbf{A} \cdot d\mathbf{l}$$

Ans: Given two magnetic vector

potential $A = -\frac{\mu_0}{4\pi} q_2$ wib/m, calculate

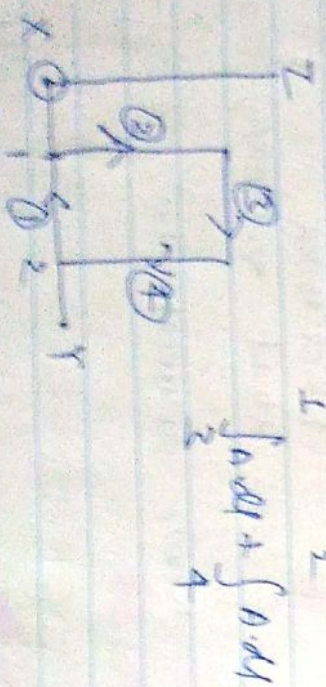
the total magnetic flux crossing

the surface $\phi = \frac{\mu_0}{2}$; $1 \leq \rho \leq 2$ m.

$$0 \leq z \leq 5 \text{ m.}$$

Soln:

$$\psi = \oint \mathbf{A} \cdot d\mathbf{l} = \int \mathbf{A} \cdot d\mathbf{l}_1 + \int \mathbf{A} \cdot d\mathbf{l}_2 + \int \mathbf{A} \cdot d\mathbf{l}_3 + \int \mathbf{A} \cdot d\mathbf{l}_4$$



$$(\mathbf{A} \cdot d\mathbf{a}) = 0.$$

$$\int_2^5 \mathbf{A} \cdot dz \mathbf{a}_z = \int_0^5 \int_1^2 -\frac{\mu_0}{4} dz = -\frac{\mu_0}{4} \times 5$$

$$= -\frac{5}{4}$$

$$\int_1^2 \mathbf{A} \cdot d\rho \mathbf{a}_\rho = 0 \cdot \int_1^2 \rho^2 d\rho = (-1) \int_1^2 \rho^2 d\rho$$

$$= \int_1^2 -\frac{\mu_0}{4} \rho^2 d\rho = \frac{\mu_0}{4} \left[-\frac{\rho^3}{3} \right]_1^2 = \frac{\mu_0}{4} \left(-\frac{8}{3} + \frac{1}{3} \right) = -\frac{7\mu_0}{12}$$

Magnetic force: $\frac{-5}{4} + 5 = \frac{-5\mu_0}{4} + 5 = \frac{-5\mu_0}{4} + \frac{20}{4} = \frac{15}{4}$

Force due to magnetic field can be experienced in three ways

- (1) Due to moving charged particle in B field
- (2) on a current element in an external B field
- (3) Between two current elements.

Force on a charged particle:-

From Coulomb's law

$$F_e = qE$$

→ Magnetic field apply force only on moving charged particle.

$$F_m = qv \times B$$

∴ $F_m \perp v, B$, Hence there is no work done by magnetic field and no change in kinetic energy.

When both fields are present.

$$F = F_e + F_m = q[E + v \times B]$$

↑ Lorentz force eqn.

Force on a current Element :-

current element $\rightarrow Idl$

Convection current $\rightarrow J = \rho v$

$$Idl = \rho ds = J dv$$

$$\therefore Idl = J dv = \int \rho v dv = \rho v$$

$$dF_m = dQ v \times B = Idl \times B$$

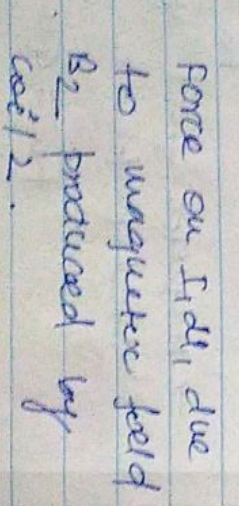
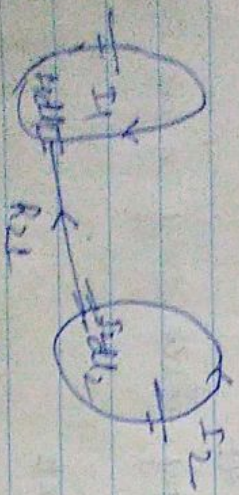
$$\therefore \text{Total force} = \int Idl \times B$$

$$(F)$$

Also,

$$F = \int \rho ds \times B \text{ or } F = \int J dv \times B$$

Force between two current elements :-



Let dB_2 be the magnetic field

$$\therefore dF_1 = I_1 dl_1 \times dB_2$$

from Biot Savart's Law

$$dB_2 = \frac{\mu_0 I_2 dl_2 \times a_{R21}}{4\pi R_{21}^2}$$

$$\therefore dF_1 = \frac{\mu_0 I_1 I_2 dl_1 \times dl_2 \times a_{R21}}{4\pi R_{21}^2}$$

$$= \frac{\mu_0 I_1 I_2 \times (I_2 dl_2 \times a_{R21})}{4\pi R_{21}^2}$$

$$\therefore \text{Total force} = \int \int \left(\frac{\mu_0 I_1 I_2}{4\pi} \right) \frac{dl_1 \times (dl_2 \times a_{R21})}{R_{21}^2}$$

Ques:- A charged particle of mass 2×10^{-30} kg and charge $3e$ starts at point $(1, -2, 0)$ with velocity $4ax + 3ay$ m/s in an E field $10ax + 10ay$ V/m. At time $t = 1$ s find

(a) Acceleration

Ans:- \checkmark

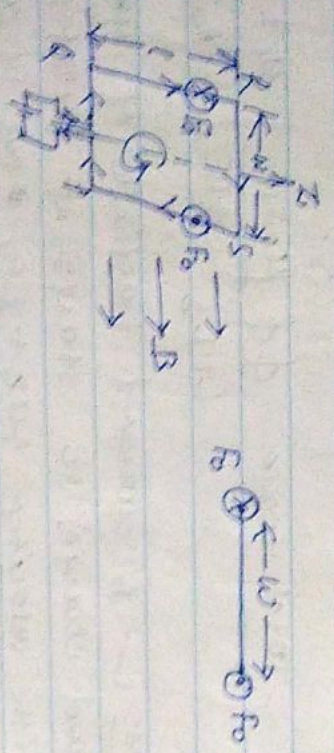
Ans:- \checkmark

Ans:- \checkmark

Ans:- \checkmark

Magnetic force and moment :-

When a ^{current} conducting loop is placed parallel to a magnetic field, it experiences a force that tends to rotate it. Torque T is the mechanical moment of force applied on the loop and defined as vector product of force and moment arm r.



$T = r \times F$; Unit \rightarrow N-m

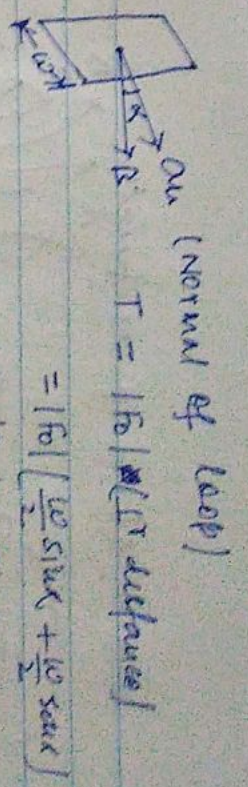
Let rectangular loop of length 'l' and width 'b' is placed in uniform magnetic field

$$F = I \int_R^L dl \times B + I \int_S^0 dl \times B + 0 + 0$$

$$= I \int_0^l dl z \times B + I \int_0^l dl z \times B$$

$F = F_0 - F_0 = 0 \rightarrow$ Overall force on the loop is zero.

But F_0 & $-F_0$ occurs at different point on the loop.



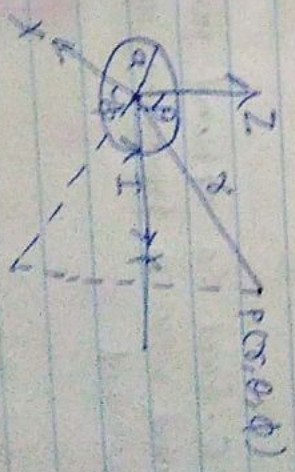
$T = |F_0| \left[\frac{l}{2} \sin \alpha + \frac{l}{2} \sin \alpha \right]$

$T = IBS \sin \alpha$
 $= (B) (IS \sin \alpha) = IS_{eq} \times B$
 where $IS_{eq} = \text{Magnetic moment (m)}$
 Unit $\rightarrow A \cdot m^2$

$T = I \times B$

Magnetic Dipole :-

Can magnet or elementary current loop is known as magnetic dipole.



$A = \frac{I \pi a^2}{4\pi r^2}$

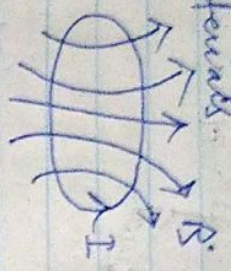
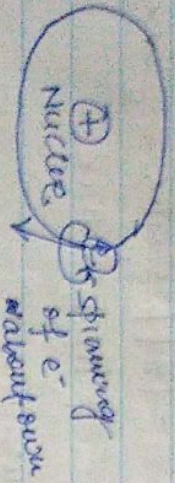
$dA = a^2 \sin \theta d\theta$

$A = \frac{I \pi a^2}{4\pi r^2}$

$B = \frac{\mu_0 I a^2}{4\pi r^3} (2 \cos \theta \hat{r} + \sin \theta \hat{\theta})$

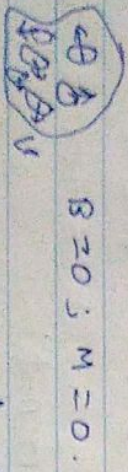
Assignment

magnetization in materials



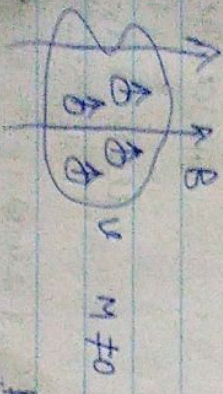
due to spinning of e^- about their own axis, an internal magnetic field is created ~~around~~ the nucleus. similar to the magnetic field created by current loop.

magnetic moment of current loop, $m = I \cdot S_{\text{area}}$
 \rightarrow in the absence of external magnetic field, algebraic sum of all moments is zero due to the random orientation of loop.



$B = 0 ; M = 0$

\rightarrow when external B-field is applied portion of loops get aligned with B producing non-zero magnetic moment.



$M \neq 0$

per unit volume

\rightarrow net magnetic moment is known as magnetization

$$M = \frac{1}{\Delta V} \sum_{i=1}^N \mu_i$$

Above magnetization leads to some current given by $I_b = \nabla \times M$

$K_b = M \times a_n$

$I_b \rightarrow$ bound volume current density or, magnetization volume current density and K_b is bound surface current density.

$\rightarrow M$ is analogous to polarization P in dielectrics $\rightarrow M$ is also known as magnetization density.

$B = \mu_0 (H + M)$

$M = \chi_m H$

$B = \mu_0 (1 + \chi_m) H$

$= \mu_0 \mu_r H$

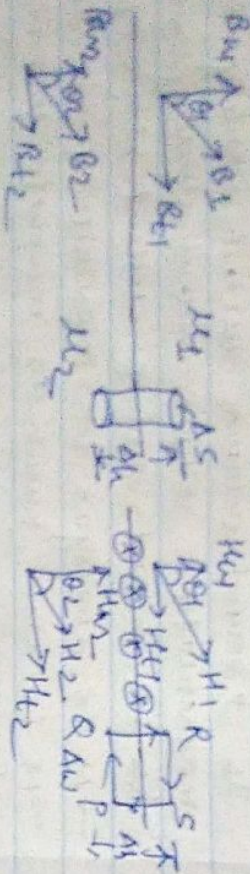
where $\mu_r = 1 + \chi_m$

Magnetic Boundary Conditions:-

Gauss Law for magnetic field:-

$$\nabla \cdot \mathbf{B} = 0 \Rightarrow \oint \mathbf{B} \cdot d\mathbf{s} = 0$$

Ampere's Circ Law, $\oint \mathbf{H} \cdot d\mathbf{l} = I$



Consider the boundary betw two media characterised by μ_1 and μ_2 respectively.

When $\Delta h \neq 0$ $\phi_{e,ds} = 0$

$$\rightarrow B_{1n} \Delta s = B_{2n} \Delta s = 0$$

$$\rightarrow B_{1n} = B_{2n}$$

$$\mu_1 H_{1n} = \mu_2 H_{2n}$$

\rightarrow Normal component of \mathbf{B} is continuous across the boundary.

\rightarrow Normal component of \mathbf{H} is discontinuous.

Let K is surface current on boundary.

$$\text{Applying } \oint \mathbf{H} \cdot d\mathbf{l} = I$$

$$\oint \mathbf{B} \cdot d\mathbf{s} \Rightarrow H_1 \Delta w - H_2 \Delta w + \mu_1 \frac{\Delta h}{2} + \mu_2 \frac{\Delta h}{2}$$

$$- \mu_2 \frac{\Delta h}{2} - \mu_1 \frac{\Delta h}{2} = K \Delta w$$

When $\Delta h = 0$

$$\left[H_1 - H_2 = K \right] \Rightarrow (H_1 - H_2) \times \mathbf{a}_{n2}$$

When surface current exist then tangential component of \mathbf{H} is also discontinuous.

$$\frac{B_{1t}}{\mu_1} - \frac{B_{2t}}{\mu_2} = K$$

When free current density, $K = 0$

$$H_1 = H_2 \Rightarrow \frac{B_1}{\mu_1} = \frac{B_2}{\mu_2}$$

Now, $B_1 \cos \theta = B_2 \cos \theta \Rightarrow$ (1)

$$H_1 = H_2$$

$$\frac{B_{1t}}{\mu_1} \sin \theta = \frac{B_{2t}}{\mu_2} \sin \theta \Rightarrow$$
 (2)

Dividing:-

$$\frac{\tan \theta}{\tan \theta} = \frac{\mu_1}{\mu_2}$$

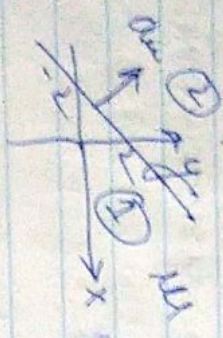
Ques: Given $H_1 = -20x + 60y + 40z$ Norm

in region $f - x \leq 2$; where $H_2 = 5x$

(a) find M_1 and B_1

(b) H_2 and B_2 in region $f - x > 2$ where

$M_2 = \frac{216}{\sqrt{2}}$



is unit normal vector for any face f

$a_n = \frac{\nabla f}{|\nabla f|}$

$f = y - x - z$

$\nabla f = \frac{\partial f}{\partial x} \mathbf{i} + \frac{\partial f}{\partial y} \mathbf{j} + \frac{\partial f}{\partial z} \mathbf{k}$

$= 0\mathbf{i} - 1\mathbf{j} + 0\mathbf{k}$

$\therefore a_n = \frac{-0\mathbf{i} + 0\mathbf{j} + 0\mathbf{k}}{\sqrt{1}}$

Now, $M_1 = \chi_{\text{vol}} H_1 = (11\mathbf{i} - 1)\mathbf{j}$

$= -90z + 240y + 160z$

(b) $H_1 \times (H_2 \cdot a_n) a_n$

$= \frac{1}{\sqrt{2}} \left[(-20\mathbf{i} + 60\mathbf{j}) \cdot \left(\frac{-1\mathbf{j}}{\sqrt{2}} \right) \right] \left[\frac{-1\mathbf{j}}{\sqrt{2}} \right]$

$= \frac{-90z}{\sqrt{2}} \left[\frac{-1\mathbf{j}}{\sqrt{2}} \right]$

$= \left[\frac{2+6}{2} \right] \left[-0\mathbf{i} + 0\mathbf{j} \right]$

$= -40z + 40y$

$\therefore H_1 = H_1 - H_2 = 20x + 60y + 40z$

Now, $H_2 = H_2 = 20x + 20y + 45z$

$H_{12} = \frac{H_1}{\sqrt{2}} \cdot \frac{H_2}{\sqrt{2}} = -10\mathbf{i} + 10\mathbf{j}$

$\therefore H_1 = H_{12} + H_{22} = -80z + 120y + 45z$

$B_2 = 11\mathbf{i} \mathbf{j}$

- static electric and magnetic fields are independent of each other.
- whereas in dynamic EM these two are interdependent.
- Time varying fields are represented by $E(x, y, z, t)$ and $H(x, y, z, t)$.

- static charge → Electrostatic field
- constant current → Magnetostatic "
- Time-varying current → EM field (waves)
- Hence variable fields
- Faraday's Law ⇒ Electromotive force
- Displacement current

Faraday's Law:

- static magnetic field produce no flow of current.
- But a time varying field produces an induced voltage (electromotive force) or emf in a closed ckt, which causes flow of current.

is equal to rate of change of magnetic flux linkage by the ckt.

$$V_{\text{ind}} = - \frac{d\phi}{dt}$$

if there is 'N' no. of turns in ckt.

$$V_{\text{ind}} = - N \frac{d\phi}{dt}$$

ϕ is the flux through a single turn
 → -ve sign shows that induced voltage acts in such a way that it opposes the flux producing it.

→ Direction of induced flux in the ckt is such that the induced magnetic field produced by the induced current will oppose the change in original magnetic field.

$$\text{Let } N = 1.$$

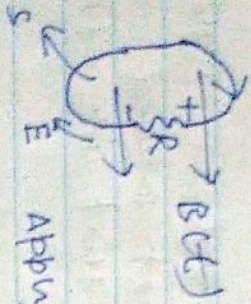
$$V_{\text{ind}} = - \frac{d\phi}{dt}$$

$$\rightarrow \oint E \cdot dl = - \frac{d}{dt} \int_S B \cdot dS$$

where, B is magnetic field and S surface area of ckt bounded by L .
 → Here E and B are inter related.

Time varying flux may exist, when -

- ① Stationary loop & time varying B.
- ② Time varying ϕ & static B.
- ③ _____ time varying ϕ .
- ④ Stationary loop in time varying B (Transformer action) :-



Applying Stokes theorem

$$\int_S (\nabla \times \mathbf{E}) \cdot d\mathbf{s} = - \int_{\partial S} \frac{\partial \mathbf{B}}{\partial t} \cdot d\mathbf{s}$$

Maxwell's eqn for $\nabla \times \mathbf{E} = - \frac{\partial \mathbf{B}}{\partial t}$ time varying field.

* IS Energy conservation violated \rightarrow ? since $\nabla \times \mathbf{E} \neq 0$.

solⁿ: NO since, work done on charge was done alone by the B(f).

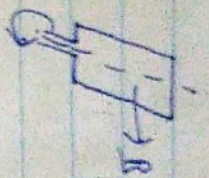
- ⑤ Moving loop in static B-field :- (Motional EMF) \rightarrow current for action.

change moving with velocity u.

$$F_m = q \times u \times B$$

$$\therefore \text{Vemf} = \oint_S \mathbf{E} \cdot d\mathbf{l} = \oint_C (\mathbf{u} \times \mathbf{B}) \cdot d\mathbf{l}$$

Next:-



Rod is moving with pair of rails with velocity u.

$$F_m = I l \times B = I l B.$$

$$\text{Vemf} = \oint_C (\mathbf{u} \times \mathbf{B}) \cdot d\mathbf{l} = \int_C (\mathbf{u} \times \mathbf{B}) \cdot d\mathbf{l}$$

$$= \int_S [\nabla \times (\mathbf{u} \times \mathbf{B})] \cdot d\mathbf{s}$$

$$\nabla \times \mathbf{E}_m = \nabla \times (\mathbf{u} \times \mathbf{B}).$$

Moving loop in time varying field

$$\text{Vemf} = \oint_C \mathbf{E} \cdot d\mathbf{l}$$

$$= - \int_S \frac{\partial \mathbf{B}}{\partial t} \cdot d\mathbf{s} + \oint_C (\mathbf{u} \times \mathbf{B}) \cdot d\mathbf{l}$$

$$\rightarrow \nabla \times \mathbf{E} = - \frac{\partial \mathbf{B}}{\partial t} + \nabla \times (\mathbf{u} \times \mathbf{B})$$

Displacement current:-

For static field, $\nabla \times \mathbf{H} = \mathbf{J}$

Taking divergence,

$$\nabla \cdot (\nabla \times \mathbf{H}) = 0 = \nabla \cdot \mathbf{J} \rightarrow \text{---}$$

From the continuity eqn

$$\nabla \cdot \mathbf{J} = - \frac{\partial \rho_v}{\partial t} \neq 0 \rightarrow \text{---}$$

There is a need for varying field (1)

and (2) are not compatible.

There should be some modification

$$\nabla \times \mathbf{H} = \mathbf{J} + \mathbf{I}_d$$

Taking divergence,

$$\nabla \cdot (\nabla \times \mathbf{H}) = 0 = \nabla \cdot \mathbf{J} + \nabla \cdot \mathbf{I}_d$$

$$\nabla \cdot \mathbf{J} = - \nabla \cdot \mathbf{I}_d$$

$$\nabla \cdot \mathbf{J} = \frac{\partial \rho_v}{\partial t} = \frac{\partial}{\partial t} (\nabla \cdot \mathbf{D})$$

$$\nabla \cdot \mathbf{I}_d = \nabla \cdot \frac{d\mathbf{D}}{dt}$$

$$\frac{d}{dt} \left[\frac{\partial \mathbf{D}}{\partial t} \right] = \frac{\partial \mathbf{I}_d}{\partial t}$$

$$\therefore \left[\nabla \times \mathbf{H} = \mathbf{J} + \frac{d\mathbf{D}}{dt} \right]$$

Maxwell eqn for time varying field.

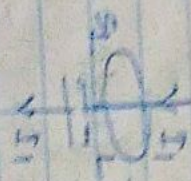
field.

Displacement current.

$$\mathbf{I}_d = \int \mathbf{J}_d \cdot d\mathbf{a} = \int \frac{d\mathbf{D}}{dt} \cdot d\mathbf{a}$$

Displacement current exists when there is time varying E-field.

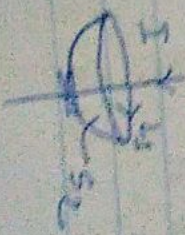
Ex: A capacitor through capacitor when alternating voltage source is applied.



$$\oint \mathbf{H} \cdot d\mathbf{l} = \int \mathbf{J} \cdot d\mathbf{S} = I_1$$

I1 is constant through capacitor. S1 is the surface area of loop L.

Taking a closed surface that passes through the capacitor plates. Ampere's law's between



$$\oint \mathbf{H} \cdot d\mathbf{l} = \int \mathbf{J} \cdot d\mathbf{S} = I_1 - I_2 = 0$$

Because there is no induced current through S_2 .

→ There are the conducting surfaces. So to avoid this, some another current concept should be present. i.e. displacement current J_d .

Total current density = $J + J_d$
 Now, here $J_d = 0$.

for case (2) :-

$$\oint H \cdot ds = \int_{S_2} (J + J_d) \cdot ds$$

$$= \int_{S_2} J_d \cdot ds = \frac{d}{dt} \int_{S_2} D \cdot ds = \frac{dQ}{dt}$$

→ Here in case (1) we have conduct current but in case (2), we have displacement current.

Ques. a. free space $E = 20000 \text{ (out -)}$
 calculate J_d & H .

Soln: $J_d = \frac{d}{dt} (D)$

$$\nabla \times E = - \frac{dA}{dt}$$

$\frac{\partial}{\partial x}$	$\frac{\partial}{\partial y}$	$\frac{\partial}{\partial z}$	
E_x	E_y	E_z	

$$= - (\mu_0) \frac{dD}{dt}$$

Maxwell's eqn: -

$$\nabla \cdot D = \rho \quad \oint D \cdot ds = Q$$

$$\nabla \cdot B = 0 \quad \oint B \cdot ds = 0$$

$$\nabla \times E = - \frac{\partial B}{\partial t} \quad \oint E \cdot dl = - \frac{\partial}{\partial t} \int B \cdot ds \text{ Faraday's}$$

$$\nabla \times H = J + \frac{dD}{dt} \quad \oint H \cdot dl = \int (J + \frac{dD}{dt}) \cdot ds \text{ Ampere Law.}$$

Time Harmonic fields:

→ Time harmonic field varies periodically or sinusoidally with time.

Phasor:

For any complex no. $z = x + jy$, phasor is given by

$$z = r \angle \phi$$

$$z = r e^{j\phi} = r (\cos \phi + j \sin \phi)$$

$$r = \sqrt{x^2 + y^2} \quad \phi = \tan^{-1}(y/x)$$

$$z_1 = x_1 + jy_1 = r_1 \angle \phi_1$$

$$z_2 = x_2 + jy_2 = r_2 \angle \phi_2$$

$$z_1 z_2 = r_1 r_2 \angle \phi_1 + \phi_2$$

$$\frac{z_1}{z_2} = \frac{r_1}{r_2} \angle \phi_1 - \phi_2$$

$$\sqrt{z} = \sqrt{r} \angle \phi/2$$

$$z^* = r \angle -\phi$$

For time element, $\theta = \omega t + \theta$

$$z = r e^{j\theta} = r e^{j\omega t} e^{j\theta}$$

$$\text{Re}(z e^{j\theta}) = r \cos(\omega t + \theta)$$

$$\text{Im}(z) = r \sin(\omega t + \theta)$$

Complex form $r e^{j\theta}$ is called phasor form.

Instantaneous form is $\text{Re}(z e^{j\theta})$

iff

→ Phasor can be scaled or varied

iff $A(x, y, z, t)$ is time harmonic field

Phasor form is $A = \text{Re}(A_0 e^{j\omega t})$

Phasor form

$$A = A_0 \cos(\omega t - \phi) \hat{a}_y$$

$$A = \text{Re}(A_0 e^{j(\omega t - \phi)} \hat{a}_y)$$

Phasor form is $A_0 = A_0 e^{j\phi} \hat{a}_y$

$$\frac{\partial A}{\partial t} = \frac{\partial}{\partial t} \text{Re}(A_0 e^{j(\omega t - \phi)} \hat{a}_y) = \text{Re}(j\omega A_0 e^{j\omega t} \hat{a}_y)$$

$$= \text{Re}(j\omega A_0 e^{j\omega t})$$

$$\frac{\partial A}{\partial t} \rightarrow j\omega A_0$$

$$\int \cos t \rightarrow \frac{\sin t}{\omega}$$

EM waves - Radio waves, TV signal, radar, signal, light.

Characteristics:-

- (1) Travel with large velocity
- (2) Follow the properties of waves
- (3) Radiate outward from the source.

Medium characteristics:- $[G, \mu, \epsilon]$

Free space:- $G = 0, \epsilon = \epsilon_0, \mu = \mu_0$

Lossless dielectric:- $G = 0, \epsilon = \epsilon_0 \epsilon_r, \mu = \mu_0 \mu_r$

$\mu = \mu_0 \mu_r$
 $\rightarrow G < \omega \epsilon$

Lossy dielectric:- $G \neq 0, \epsilon = \epsilon_0 \epsilon_r, \mu = \mu_0 \mu_r$

Good conductors:- $G = \infty, \epsilon = \epsilon_0, \mu = \mu_0$

$\rightarrow G \gg \omega \epsilon$

$\omega =$ Angular frequency of wave.

Wave Propagation in lossy dielectric:-

\rightarrow EM waves propagating in lossy dielectric losses power due to imperfect dielectric (partially conducting medium)

\rightarrow Consider a lossless, isotropic, homogeneous, lossy dielectric medium

From Maxwell's eqns:-

$\nabla \cdot E_s = 0$ [since, $\rho_v = 0$]

$\nabla \cdot H_s = 0$ \rightarrow (1)

$\nabla \times E = -\frac{dB}{dt} = -j\omega \mu H_s$ \rightarrow (2)

$\nabla \times H = J + \frac{dD}{dt} = G E_s + j\omega \epsilon E_s$

$\rightarrow \nabla \times H = [G + j\omega \epsilon] E_s$ \rightarrow (3)

Taking curl of eqn (3):-

$\nabla \times \nabla \times E_s = -j\omega \mu [\nabla \times H_s]$

Since, $\nabla \times (\nabla \times A) = \nabla(\nabla \cdot A) - \nabla^2 A$

$\therefore \nabla(\nabla \cdot E_s) - \nabla^2 E_s = -j\omega \mu (\nabla \times H_s)$

Using eqn (1) and (2)

$\nabla^2 E_s = j\omega \mu [G + j\omega \epsilon] E_s$

$\nabla^2 E_s - \gamma^2 E_s = 0$

where, $\gamma = \sqrt{j\omega \mu [G + j\omega \epsilon]}$

γ is called propagation constant of medium.

Similarly, $\nabla^2 H_s - \gamma^2 H_s = 0$

\rightarrow These equations are known as Helmholtz eqn. vector wave equations.

$$r^2 = j\omega\mu(\epsilon + j\omega\epsilon)$$

$$r = \alpha + j\beta$$

$$\operatorname{Re}(r^2) = \operatorname{Re}[-\omega^2\mu\epsilon + j\omega\mu\epsilon^2]$$

$$= -\omega^2\mu\epsilon$$

$$|r|^2 = \alpha^2 + \beta^2 = \left[\epsilon^2 + (\omega\epsilon)^2 \right] \omega\mu$$

$$\operatorname{Re}(r^2) = \operatorname{Re}(\alpha^2 + j2\alpha\beta - \beta^2) = \alpha^2 - \beta^2$$

$$\therefore \alpha^2 - \beta^2 = -\omega^2\mu\epsilon$$

$$\text{and, } \alpha^2 + \beta^2 = \omega\mu \sqrt{\alpha^2 + (\omega\epsilon)^2}$$

$$\text{solving, } \alpha = \omega \sqrt{\frac{\mu\epsilon}{2} \left[\sqrt{1 + \left(\frac{\epsilon}{\omega\epsilon}\right)^2} - 1 \right]}$$

$$\beta = \omega \sqrt{\frac{\mu\epsilon}{2} \left[\sqrt{1 + \left(\frac{\epsilon}{\omega\epsilon}\right)^2} + 1 \right]}$$

Let wave is propagating in z-direction and E has only x-component

$$\text{then } E = E_x(z) a_x$$

$$\nabla^2 E - r^2 E = 0$$

$$(\nabla^2 - r^2) E_x(z) = 0$$

$$\frac{\partial^2 E_x(z)}{\partial z^2} + \frac{\partial^2 E_x(z)}{\partial y^2} + \frac{\partial^2 E_x(z)}{\partial z^2} - r^2 E_x(z) = 0$$

$$\therefore \left[\frac{\partial^2}{\partial z^2} - r^2 \right] E_x(z) = 0$$

$$\therefore E_x = E_0 e^{-r^2 z} + E_0' e^{r^2 z}$$

E_0 and E_0' are constants.

Since field should be finite at $z \rightarrow \infty$, $E_0' = 0$.

$$\therefore E_0' = 0$$

$\rightarrow e^{-r^2 z}$ indicates that wave propagating along

$-z$, but assumption is that it is along $+z$.

$$\therefore E_0' > 0$$

Introducing phase factor $e^{j\omega t}$

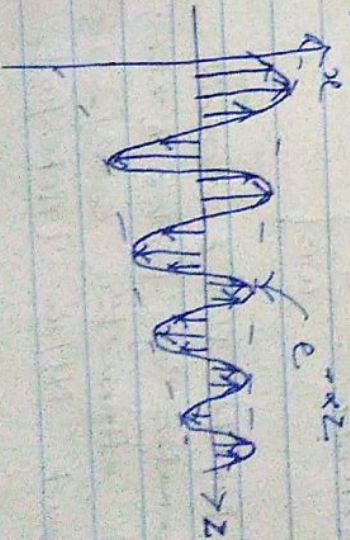
$$E_x(z, t) = E_0 e^{-(\alpha + j\beta)z} e^{j\omega t}$$

Instantaneous value,

$$E_x(z, t) = E(z, t) a_x$$

$$E(z, t) = \operatorname{Re} \left[E_0 e^{-(\alpha + j\beta)z} e^{j\omega t} a_x \right]$$

$$E(z, t) = E_0 e^{-\alpha z} \cos(\omega t - \beta z) a_x$$



$$\nabla \times \mathbf{E} = -\mu \frac{d\mathbf{H}}{dt} \Rightarrow \mathbf{H} = -\frac{1}{\mu} \int (\nabla \times \mathbf{E}) dt$$

$$\nabla \times \mathbf{E} = \begin{pmatrix} \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ E_x & 0 & 0 \end{pmatrix}$$

$$= a_x(0-0) + a_y \left[\frac{\partial}{\partial z} E_x - 0 \right] - 0 \cdot a_z$$

$$= \frac{\partial}{\partial z} E_x a_y$$

since, $E_x(z,t) = E_0 e^{-\alpha z} \cos(\omega t - \beta z)$

$$\therefore \mathbf{H}(z,t) = \frac{E_0}{\mu} e^{-\alpha z} \cos(\omega t - \beta z - \theta_n) a_y$$

$$\frac{E_0}{\mu} e^{-\alpha z} \cos(\omega t - \beta z) a_y$$

where $\theta_n = \sqrt{\frac{\sigma \mu \omega}{\epsilon + j\sigma \mu}} = |\eta| \angle \theta_n = |\eta| e^{j\theta_n}$

$$\tan 2\theta_n = \frac{\sigma}{\omega \epsilon}$$

→ wave propagation in z-direction.

It attenuates by factor $e^{-\alpha z}$;

∴ α is attenuation coeff.

Wave η (Np/m) (Nepers/m).

$$\eta = 20 \log_{10} e = 8.686 \text{ dB}$$

→ I vector indicates reduces to e^{-1} of original value.

$$\alpha = \omega \sqrt{\frac{\mu \epsilon}{2} \left[\sqrt{1 + \left(\frac{\sigma}{\omega \epsilon}\right)^2} - 1 \right]}$$

where, $\sigma = 0, \alpha = 0$

i.e. when lossless medium or free space, there

is no attenuation i.e. wave no

→ β is phase measure of phase shift per unit

length. Unit → Radian/m.

$$\beta = \frac{\omega}{v} \quad \text{and} \quad \beta = \frac{2\pi}{\lambda}$$

→ \mathbf{E} & \mathbf{H} are out of phase by θ_n at

any instant of time due to complex intrinsic impedance of medium.

→ \mathbf{E} leads \mathbf{H} by θ_n .

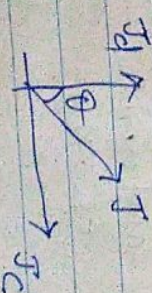
For lossy medium,

$$\frac{|\mathbf{H}|}{|\mathbf{E}|} = \frac{\sigma}{\omega \epsilon} = \frac{\sigma}{\omega \epsilon} = \tan \delta$$

$$\tan \delta = \frac{\sigma}{\omega \epsilon}$$

→ $\tan \delta$ is loss tangent

δ is loss angle



(1)

Loss tangent, $\tan \delta = \frac{\sigma}{\omega \epsilon}$

$$P = \omega \sqrt{\frac{\mu \epsilon}{2}} \left[\sqrt{1 + \left[\frac{\sigma}{\omega \epsilon} \right]^2} + 1 \right]$$

Given: $\mu = \mu_0, \epsilon = 5 \mu \epsilon_0$

$$\epsilon = \epsilon_0, f = 5 \text{ MHz}$$

$$\frac{1}{\text{Wavelength}} = c = 3 \times 10^8$$

$$W_p = \frac{1}{\sqrt{\mu \epsilon}}$$

$$\frac{E}{W_p} = V$$

$$+ C = (V) \times W_p$$

(2)

Reflection and transmission of EM waves:-

Direction of propagation: $D_1 \rightarrow D_2$

(a) Normal incidence:

Material 1

$$\epsilon_1, \mu_1$$

Material 2

$$\epsilon_2, \mu_2$$

Incident wave $\rightarrow E_0 e^{j\omega t}$

$E_0 e^{j\omega t}$

$$E = n_1 H$$

$$\therefore E_1 = n_1 H_1$$

$$E_2 = n_2 H_2$$

$$E_r = -n_1 H_r$$

When wave reflected, propagation constant changes and one of the field values also change its sense either E or H

Incident

$$E_x \quad H_y$$

$$a_x \quad a_y \rightarrow a_z$$

$$-a_x \quad a_y \rightarrow -a_z$$

$$a_x \quad -a_y \rightarrow -a_z$$

When normal incidence of wave, we can find H fields are tangential to boundary.

$$E_{T1} = E_{T2} \quad \therefore H_{T1} = H_{T2}$$

Normal

When we require boundary conditions

$$E_1 + E_r = E_2$$

$$1 + \frac{E_r}{E_1} = \frac{E_2}{E_1}$$

$$Z = \frac{E_1}{H_1}$$

$$Z = \frac{E_2}{H_2}$$

For wave $E = E_0 e^{j\omega t}$ reflected wave $E_0 e^{j\omega t}$

$$r = \frac{n_2 - n_1}{n_2 + n_1}$$

$$r = \frac{\sqrt{\epsilon_2} - \sqrt{\epsilon_1}}{\sqrt{\epsilon_2} + \sqrt{\epsilon_1}}$$



$$r = \frac{n_2 - n_1}{n_2 + n_1}$$

$$r = \frac{\sqrt{\epsilon_2} - \sqrt{\epsilon_1}}{\sqrt{\epsilon_2} + \sqrt{\epsilon_1}}$$

power $E_1 > E_2$ $E_r < +ve$

$$E_r > E_i$$

$$E_r > E_i$$

$$E_H = -ve$$

$$E_H < L$$

$$r_p = -ve$$

$$1 + r_p = r_p \Rightarrow r_p < L$$

$$r = \frac{\sqrt{\epsilon_1} - \sqrt{\epsilon_2}}{\sqrt{\epsilon_1} + \sqrt{\epsilon_2}}$$

$E_r = |r| + E_i \Rightarrow$ collector, E_{avg}

$$\frac{E_r}{E_i} = r$$

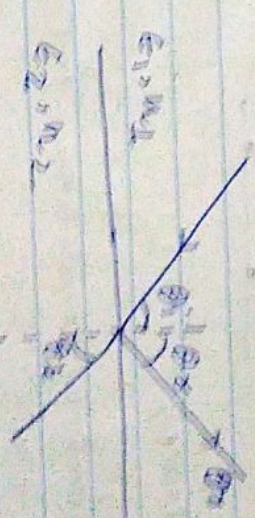
$\Rightarrow E_r = v$ for D boundary
again for 2nd boundary

$$E_i = \sqrt{\epsilon_1} E_1$$

$$E_r = v$$

$$\frac{E_r}{E_i} = v \Rightarrow E_r = v E_i$$

oblique incidence (continued)



$$\frac{\sin \theta_i}{\sin \theta_r} = \sqrt{\frac{\epsilon_2}{\epsilon_1}}$$

$$\theta_i = \theta_r$$

for critical angle $\theta_c = 90^\circ$

$$\theta_c = \theta_c$$

$$\sin \theta_c = \sqrt{\frac{\epsilon_2}{\epsilon_1}}$$

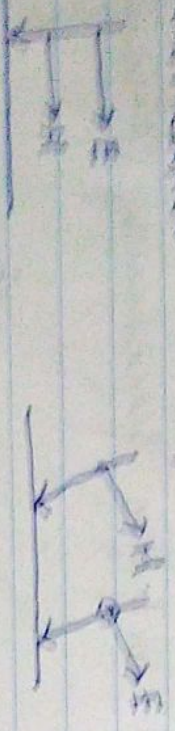


For $\theta_i = \theta_c \Rightarrow$ zero transmission and total reflection.

Polarization and reflection:



S-polarization P-polarization



(normal incidence)

E-field boundary conditions for S-polarized wave

n-polarization

$$E = \frac{n_2 \cos \theta_i - n_1 \cos \theta_r}{n_2 \cos \theta_i + n_1 \cos \theta_r}$$

$$r = \frac{n_2 \cos \theta_i - n_1 \cos \theta_r}{n_2 \cos \theta_i + n_1 \cos \theta_r}$$

and no P-polarization

$$n_1 = \frac{2n_2}{n_1 + n_2}, n_2 = \frac{2n_1}{n_1 + n_2}$$

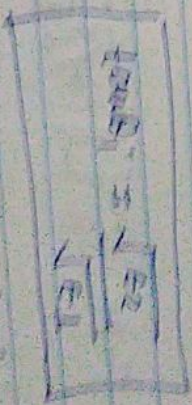
$$r_s = \frac{\cos \theta_i - \sqrt{\frac{\epsilon_2}{\epsilon_1} - \sin^2 \theta_i}}{\cos \theta_i + \sqrt{\frac{\epsilon_2}{\epsilon_1} - \sin^2 \theta_i}}$$

$$r_p = \frac{\frac{\epsilon_2}{\epsilon_1} \cos \theta_i - \sqrt{\frac{\epsilon_2}{\epsilon_1} - \sin^2 \theta_i}}{\frac{\epsilon_2}{\epsilon_1} \cos \theta_i + \sqrt{\frac{\epsilon_2}{\epsilon_1} - \sin^2 \theta_i}}$$

Now, if $r_p = 0$: complete transmission zone reflection.

$$\left(\frac{\epsilon_2}{\epsilon_1}\right)^2 (1 - \sin^2 \theta_i) = \frac{\epsilon_2}{\epsilon_1} - \sin^2 \theta_i$$

$$\rightarrow \sin^2 \theta_i = \frac{\epsilon_2}{\epsilon_1} \rightarrow \sin \theta_i = \frac{\sqrt{\epsilon_2}}{\sqrt{\epsilon_1}}$$



$\theta_i \rightarrow$ Brewster's angle θ_c incidence

$$\text{if } r_s = 0:$$

$$\epsilon_1 = \epsilon_2 \rightarrow \text{perfectly transparent}$$

∴ Brewster's angle for cross reflection for s-polarized wave for different media not exist.

$$\rightarrow \tan \theta_p = \sqrt{\epsilon}$$

→ Any two media can have θ_p .

→ exactly at $\theta_i = \theta_r$.

→ only p-polarized wave can have θ_p .

(13) $\eta = 240 < 30^\circ$

$$\rightarrow \theta_u = 30^\circ$$

$$\text{loss tangent} = \frac{G}{\omega \epsilon} = \tan \angle \theta_u$$

$$= \tan 60^\circ = \sqrt{3}$$

$$\alpha = \omega \sqrt{\frac{\mu \epsilon}{2} \left[\sqrt{1 + \left(\frac{G}{\omega \epsilon} \right)^2} - 1 \right]}$$

$$f = 1 \text{ MHz}; \omega = \sqrt{\quad}$$

$$\eta = \sqrt{\frac{\mu_0}{\epsilon}}$$

$$\rightarrow \epsilon = \sqrt{\quad}$$

$$\epsilon_c = \epsilon \left[1 - j \frac{G}{\omega \epsilon} \right]$$