PIN DIAGRAM OF 8085

Introduction to 8085



- It was introduced in 1977.
- It is 8-bit microprocessor.
- Its actual name is 8085 A.
- It is single NMOS device.
- It contains 6200 transistors approx.
- Its dimensions are 164 mm x 222 mm.
- It is having 40 pins Dual-Inline-Package (DIP).

Introduction to 8085



- It has three advanced versions:
 - ° 8085 AH
 - ° 8085 AH2
 - 8085 AH1
- These advanced versions are designed using HMOS technology.

Introduction to 8085



- The advanced versions consume 20% less power supply.
- The clock frequencies of 8085 are:
 - 8085 A 3 MHz
 - 8085 AH 3 MHz
 - 8085 AH2 5 MHz
 - 8085 AH1 6 MHz



X₁ & X₂

Pin 1 and Pin 2 (Input)

- These are also called Crystal Input Pins.
- 8085 can generate clock signals internally.
- To generate clock, a crystal(or RC,LC network) is connected at these two pins.
- The frequency is internally divided by two.



RESET IN and RESET OUT

Pin 36 (Input) and Pin 3 (Output)

RESET IN:

- It is active low signal.
- It is used to reset the microprocessor.



RESET IN and RESET OUT

Pin 36 (Input) and Pin 3 (Output)

Resetting the microprocessor

means:

- Clearing the PC and IR.
- Disabling all interrupts (except TRAP).
- Disabling the SOD pin.
- All the buses (data, address, control) are tri-stated.
- Gives HIGH output to RESET OUT pin.



RESET IN and RESET OUT

Pin 36 (Input) and Pin 3 (Output)

RESET OUT:

- It is used to reset the peripheral devices and other ICs on the circuit.
- It is an output signal.
- It is an active high signal.
- The output on this pin goes high whenever RESET IN is given low signal.
- The output remains high as long as RESET IN is kept low.



SID and SOD

Pin 4 (Input) and Pin 5 (Output)

SID (Serial Input Data):

- It takes 1 bit input from serial port of 8085.
- Stores the bit at the 8th position (MSB) of the Accumulator.
- RIM (Read Interrupt Mask) instruction is used to transfer the bit.



SID and SOD

Pin 4 (Input) and Pin 5 (Output)

- SOD (Serial Output Data):
- It takes 1 bit from Accumulator to serial port of 8085.
- Takes the bit from the 8th position (MSB) of the Accumulator.
- SIM (Set Interrupt Mask) instruction is used to transfer the bit.



Interrupt Pins

Interrupt:

- It means interrupting the normal execution of the microprocessor.
- When microprocessor receives interrupt signal, it discontinues whatever it was executing.
- It starts executing new program indicated by the interrupt signal.
- Interrupt signals are generated by external peripheral devices.
- After execution of the new program, microprocessor goes back to the previous program.

Sequence of Steps Whenever There is an Interrupt

- Microprocessor completes execution of current instruction of the program.
- PC contents are stored in stack.
- PC is loaded with address of the new program.
- After executing the new program, the microprocessor returns back to the previous program.
- It goes to the previous program by reading the top value of stack.

Five Hardware Interrupts in 8085

- TRAP
- RST 7.5
- RST 6.5
- RST 5.5
- INTR

Classification of Interrupts

• Maskable and Non-Maskable

Vectored and Non-Vectored

• Edge Triggered and Level Triggered

Maskable Interrupts

• Maskable interrupts are those interrupts which can be *enabled* or *disabled*.

• Enabling and Disabling is done by software instructions.

Maskable Interrupts

- List of Maskable Interrupts:
 - RST 7.5
 - RST 6.5
 - RST 5.5
 - INTR

Non-Maskable Interrupts

• The interrupts which are always in *enabled* mode are called non-maskable interrupts.

• These interrupts can never be disabled by any software instruction.

• TRAP is a non-maskable interrupt.

Vectored Interrupts

 The interrupts which have fixed memory location for transfer of control from normal execution.

• Each vectored interrupt points to the particular location in memory.

Vectored Interrupts

- List of vectored interrupts:
 - RST 7.5
 - RST 6.5
 - RST 5.5
 - TRAP

Vectored Interrupts

The addresses to which program control goes:

Name	Vectored Address
RST 7.5	003C H (7.5 x 0008 H)
RST 6.5	0034 H (6.5 x 0008 H)
RST 5.5	002C H (5.5 x 0008 H)
TRAP	0024 H (4.5 x 0008 H)

• Absolute address is calculated by multiplying the RST value with 0008 H.

Non-Vectored Interrupts

• The interrupts which don't have fixed memory location for transfer of control from normal execution.

• The address of the memory location is sent along with the interrupt.

• INTR is a non-vectored interrupt.

Edge Triggered Interrupts

• The interrupts which are triggered at leading or trailing edge are called edge triggered interrupts.

• RST 7.5 is an edge triggered interrupt.

 It is triggered during the leading (positive) edge.

Level Triggered Interrupts

 The interrupts which are triggered at high or low level are called level triggered interrupts.

- RST 6.5
- RST 5.5
- INTR

• TRAP is edge and level triggered interrupt.

Interrupts Priority

 Whenever there exists a simultaneous request at two or more pins then the pin with higher priority is selected by the microprocessor.

• Priority is considered only when there are simultaneous requests.

Interrupts Priority

• Priority of interrupts:

Interrupt	Priority	
TRAP	1	
RST 7.5	2	
RST 6.5	3	
RST 5.5	4	
INTR	5	

TRAP

Pin 6 (Input)

- It is an non-maskable interrupt.
- It has the highest priority.
- It cannot be disabled.
- It is both edge and level triggered.
- It means TRAP signal must go from low to high.
- And must remain high for a certain period of time.
- TRAP is usually used for power failure and emergency shutoff.



RST 7.5 Pin 7 (Input)

- It is a maskable interrupt.
- It has the second highest Reset Out priority.
- It is positive edge triggered only.
- The internal flip-flop is triggered by the rising edge.
- The flip-flop remains high until it is cleared by RESET.



RST 6.5 Pin 8 (Input)

- It is a maskable interrupt.
- It has the third highest priority.
- It is level triggered only.
- The pin has to be held high for a specific period of time.
- RST 6.5 can be enabled by El instruction.
- It can be disabled by DI instruction.



RST 5.5 Pin 9 (Input)

- It is a maskable interrupt.
- It has the fourth highest priority.
- It is also level triggered.
- The pin has to be held high for a specific period of time.
- This interrupt is very similar to RST 6.5.



INTR Pin 10 (Input)

- It is a maskable interrupt.
- It has the lowest priority.
- It is also level triggered.
- It is a general purpose interrupt.
- By general purpose we mean that it can be used to vector microprocessor to any specific subroutine having any address.



INTA Pin 11 (Output)

- It stands for interrupt acknowledge.
- It is an out going signal.
- It is an active low signal.
- Low output on this pin indicates that microprocessor has acknowledged the INTR request.



Address and Data Pins

Address Bus:

- The address bus is used to send address to memory location/IO devices.
- Unidirectional
- It selects one of the many locations in memory or IO device.
- Its size is 16-bit.

Address and Data Pins

Data Bus:

- It is used to transfer data between microprocessor and memory or IO devices.
- These buses are bidirectional.
- Data bus is of 8-bit.

AD₀ – AD₇ Pin 19-12 (Bidirectional)

- These pins serve the dual purpose of transmitting lower order address and data byte.
- During 1st clock cycle, these pins act as lower half of address.
- In remaining clock cycles, these pins act as data bus.
- The separation of lower order address and data is done by address latch.



 $A_8 - A_{15}$ Pin 21-28 (Unidirectional)

- These pins carry the higher order of address bus.
- The address is sent from microprocessor to memory/ IO device.
- These 8 pins are switched to high impedance state during HOLD and RESET mode.



ALE Pin 30 (Output)

- It is used to enable Address Latch.
- It indicates whether bus functions as address bus or data bus.
- If ALE = 1 then
 - Bus functions as address bus.
- If ALE = 0 then
 - Bus functions as data bus.



S₀ and S₁ Pin 29 (Output) and Pin 33 (Output)

- S₀ and S₁ are called Status Pins.
- They tell the current operation which is in progress in 8085.





- This pin tells whether I/O or memory operation is being performed.
- If $IO/\overline{M} = 1$ then

I/O operation is being performed.

- If IO/M = 0 then
 - Memory operation is being performed.





- The operation being performed is indicated by S₀ and S₁.
- If $S_0 = 0$ and $S_1 = 1$ then

It indicates WRITE operation.

- If $IO/\overline{M} = 0$ then
 - It indicates Memory operation.
- Combining these two we get **Memory Write** Operation.

Table Showing IO/M, S₀, S₁ and Corresponding Operations

Operations	IO/M	S ₀	S ₁
Opcode Fetch	0	1	1
Memory Read	0	1	0
Memory Write	0	0	1
I/O Read	1	1	0
I/O Write	1	0	1
Interrupt Ack.	1	1	1
Halt	Z	0	0
Hold	Z	Х	Х
Reset	Z	Х	Х

Z= Tri-state(high impedance) X= Unspecified

RD Pin 32 (Output)

- RD stands for Read.
- It is an active low signal.
- It is a control signal used for Read operation either from memory or from Input device.
- A low signal indicates that data on the data bus must be placed either from selected memory location or from input device.



WR Pin 31 (Output)

- WR stands for Write.
- It is also active low signal.
- It is a control signal used for Write operation either into memory or into output device.
- A low signal indicates that data on the data bus must be written into selected memory location or into output device.



READY Pin 35 (Input)

- This pin is used to synchronize slower peripheral devices with fast microprocessor.
- A low level causes the microprocessor to enter into *wait state*.
- The microprocessor remains in wait state until the input at this pin goes high.



HOLD

Pin 38 (Input)

- HOLD pin is used to request the microprocessor for DMA transfer.
- A high signal on this pin is a request to microprocessor to relinquish the hold on buses.
- This request is sent by DMA controller.
- Intel 8257 and Intel 8237 are two DMA controllers.



HLDA

Pin 39 (Output)

- HLDA stands for Hold Acknowledge.
- The microprocessor uses this pin to acknowledge the receipt of HOLD signal.
- When HLDA signal goes high, address bus, data bus, RD, WR, IO/M pins are *tri-stated*.
- This means they are cut-off from external environment.



HLDA

Pin 39 (Output)

- The control of these buses goes to DMA Controller.
- Control remains at DMA Controller until HOLD is held high.
- When HOLD goes low, HLDA also goes low and the microprocessor takes control of the buses.



V_{ss} and V_{cc} Pin 20 (Input) and Pin 40 (Input)

- +5V power supply connected to V_{cc}.
- Ground signal is connected to V_{ss} .

